SpeedyBee F405 V4 BLS 60A 30x30 Stack

User Manual V1.0

Contents (Click on any section to jump)

Part 1 – OverView	
 Specs Overview 	1
 Dimensions 	2
 Package 	3
FC & ESC Connection	4
Part 2 - SpeedyBee F405 V4 Flight Controller	
 Layout 	5
 FC's Peripheral Connection 	6
App & FC Configuration	7
 FC Firmware Update 	8
 Specifications 	9
Part 3 - SpeedyBee BLS 60A 4-in-1 ESC	
 Layout 	10

- Connection with Motors & Power Cable
- ESC Configuration
- ESC Firmware Update
- Specifications



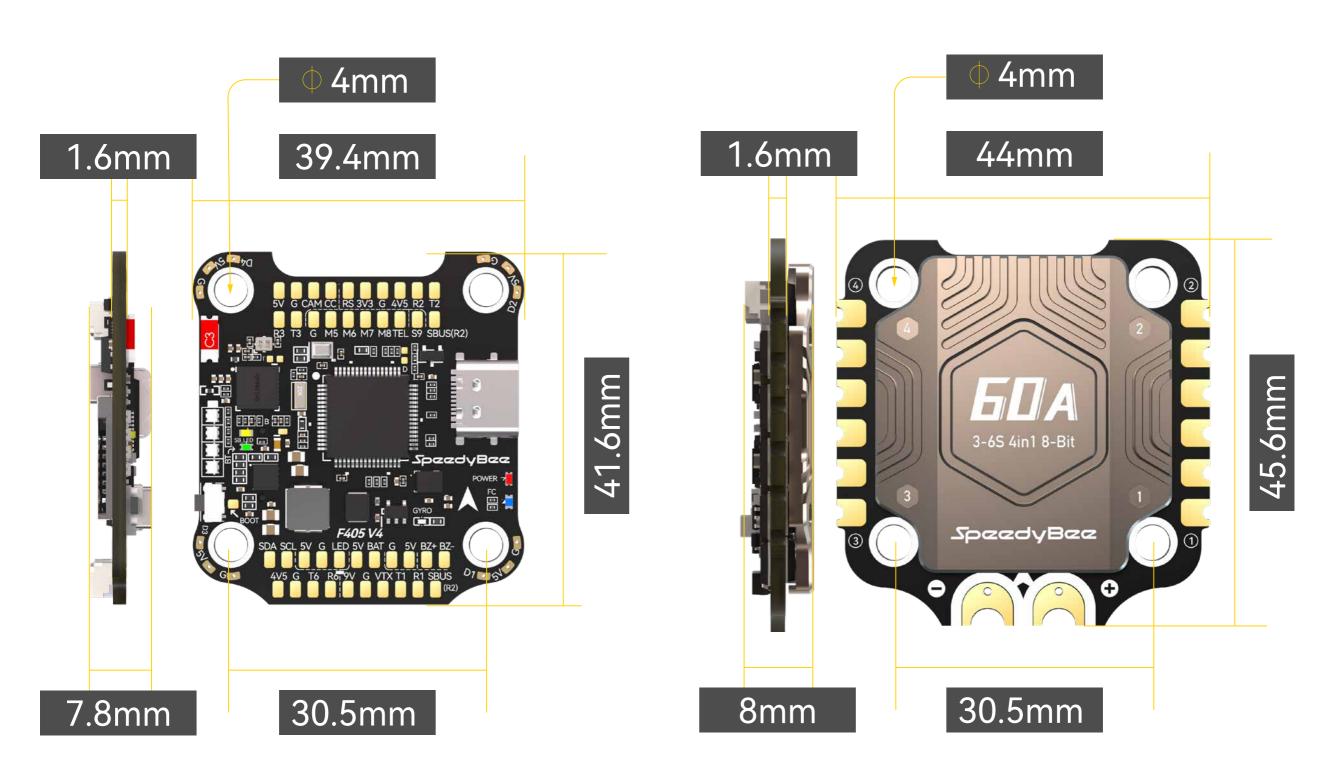
11

Part 1 - OverView

Specs Overview

1/14

Product Name	SpeedyBee F405 V4 BLS 60A 30x30 Stack
Flight Controller	SpeedyBee F405 V4 Flight Controller
ESC	SpeedyBee BLS 60A 4-in-1 ESC
Bluetooth	Supported. For FC & ESC parameter settings
Wireless FC Firmware Flashing	NOT Supported
Wireless Blackbox Dwonload & Analysis	NOT Supported
Power Input	3-6S LiPo
Mounting	30.5 x 30.5mm (4mm hole size)
Dimension	45.6mm(L) x 44mm(W) x 18.3mm(H)
Weight	34g



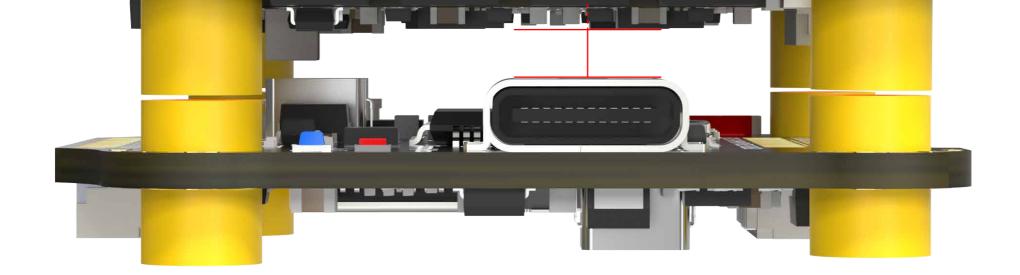


Important Stack Installation Note

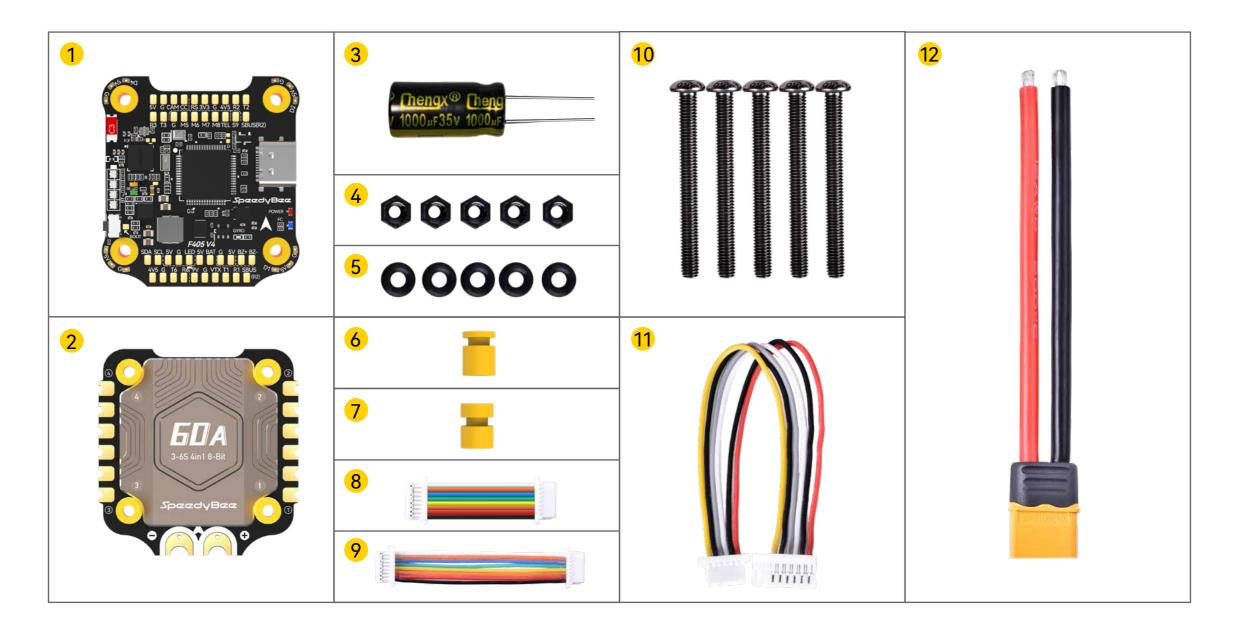
When installing your stack, adhere to the standardmounting method. The orientation of the gyro andmotor sequence can be adjusted through settingslf you opt for an inverted manner, be extra carefulabout the space between the frame, the FC, andthe ESC.

It's crucial to swap the silicone grommets when changing the positions of the FC and the ESC, as illustrated below. This step is vital to prevent any contact between the FC's USB interface and the ESC, which could lead to a short circuit. Please be aware that any damage resulting from improper installation of this nature is not covered under the warranty.

leave enough space



SpeedyBee F405 V4 60A 30x30 Stack



- 1 SpeedyBee F405 V4 Flight Controller x 1
- 2 SpeedyBee BLS 60A 4-in-1 ESC x 1
- 35V 1000uF Low ESR Capacitor x 1
- 4 M3 Nylon Nut x 5
- **5** M3 silicone O Ring x 5
- 6 M3*8mm Silicone Grommets(for FC) x 1

- 7 M3*8.1mm Silicone Grommets(for ESC) x 1
- 8 SH 1.0mm 25mm-length 8pin Cable(for FC-ESC connection) x 1
- 9 SH 1.0mm 75mm-length 8pin Cable* x 1
- **10** M3*30mm Iner-hexagon Screws x 5
- 11 DJI 6pin Cable(80mm) x 1
- **12** XT60 Power Cable(100mm) x 1

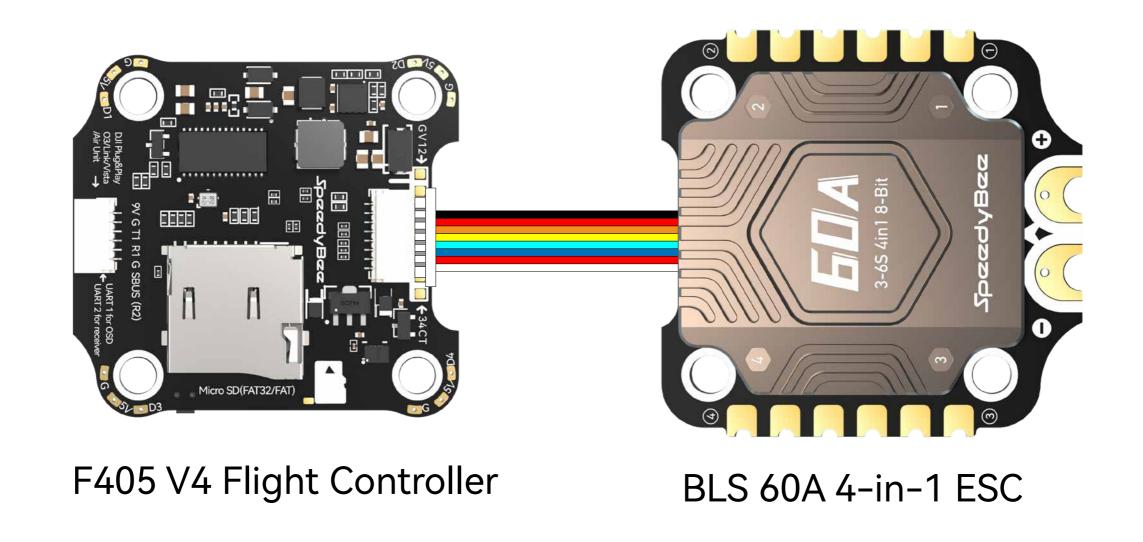
* When the ESC tail faces the drone's front, use this cable for the flight controller and ESC; both ends plug interchangeably.

FC & ESC Connection

Use the 8-pin cable in the package to connect the FC and the ESC. Or solder 8 wires directly to the 8 pads on each end.

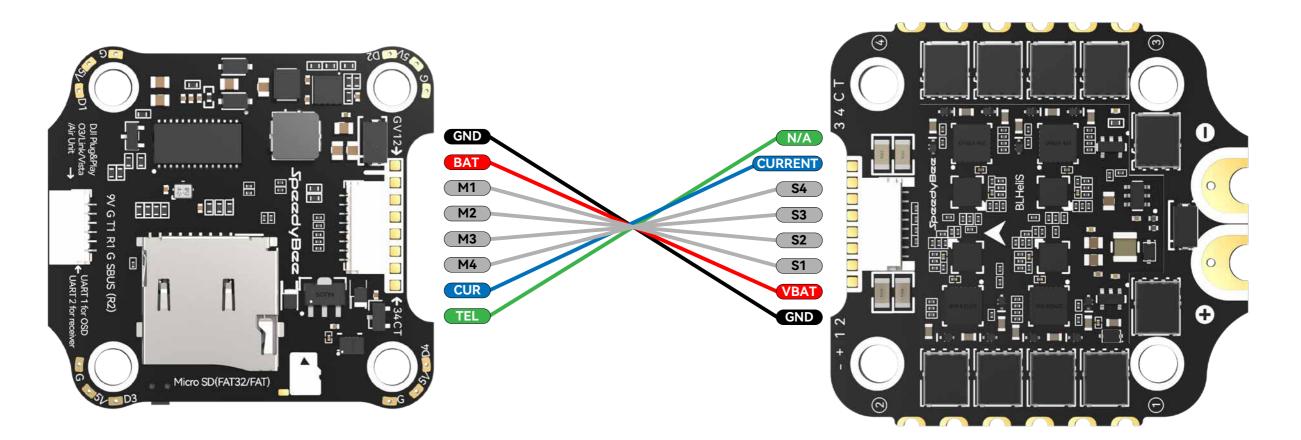
Method 1 - Using 8-pin cable

Use any end of the 8-pin JST cable to connect the FC to the ESC.



Method 2 - Direct soldering

Solder 8 wires to the 8 pads on each end referring to the pad definition below.



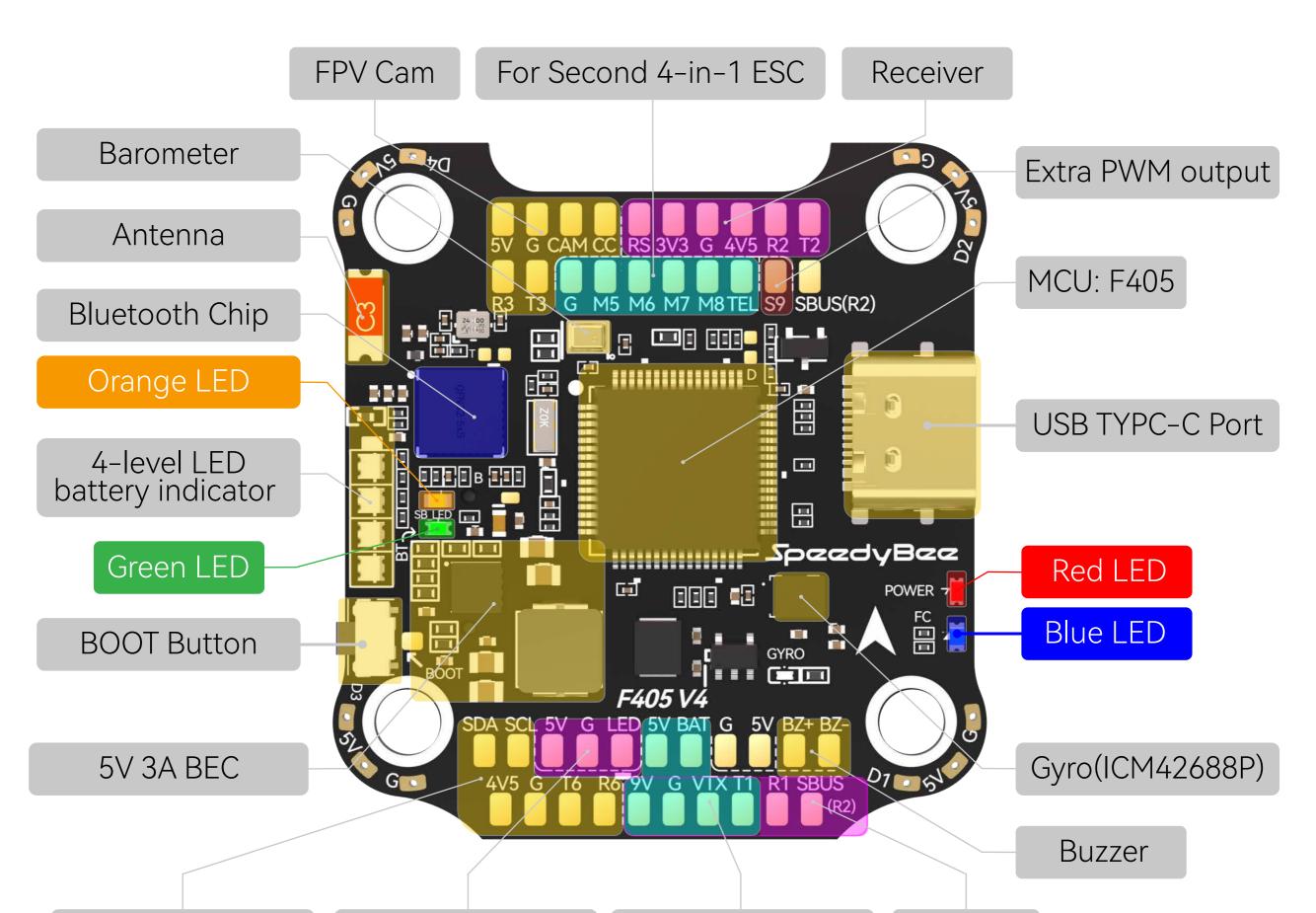
F405 V4 Flight Controller

BLS 60A 4-in-1 ESC

Part 2 – F405 V4 Flight Controller

Layout

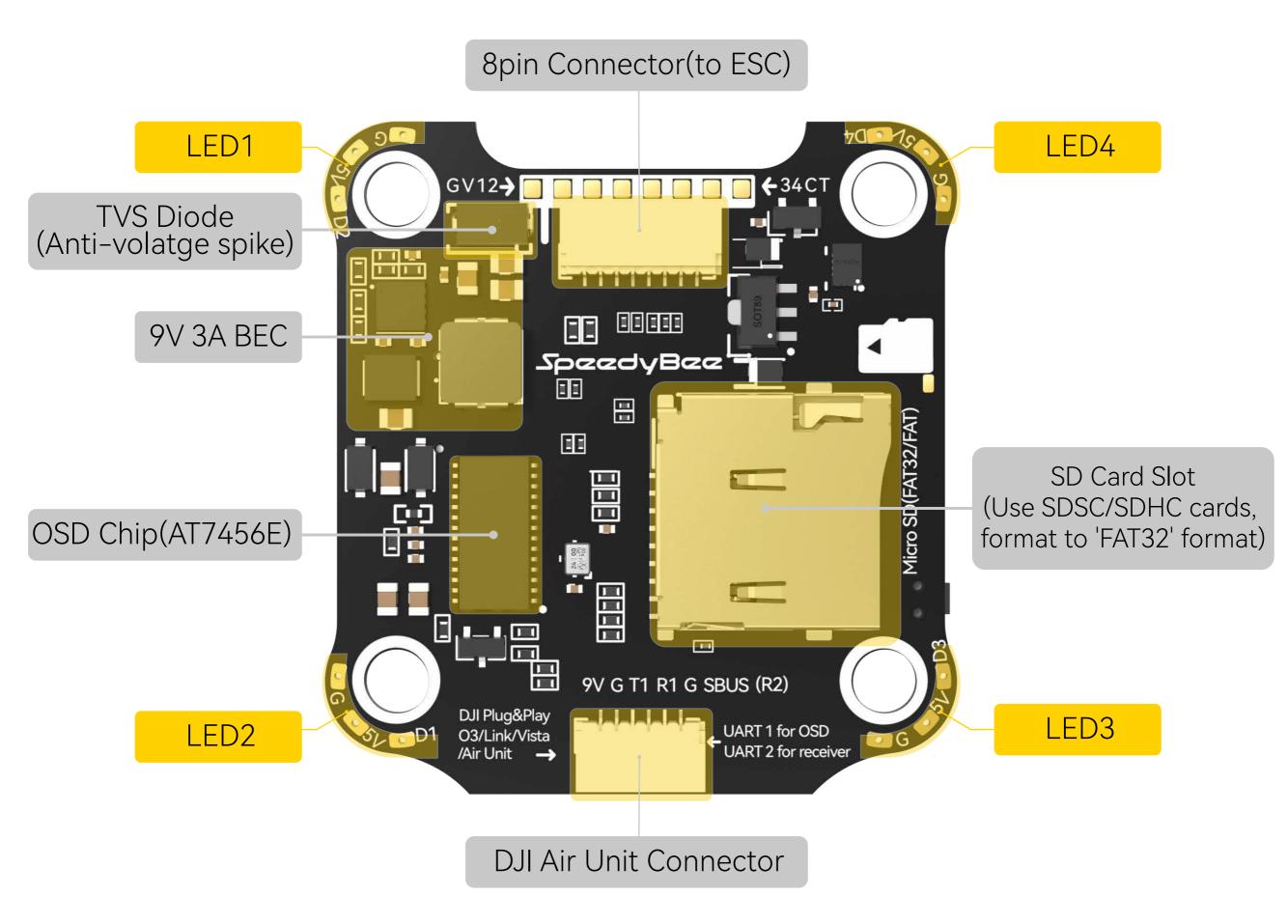
5/14



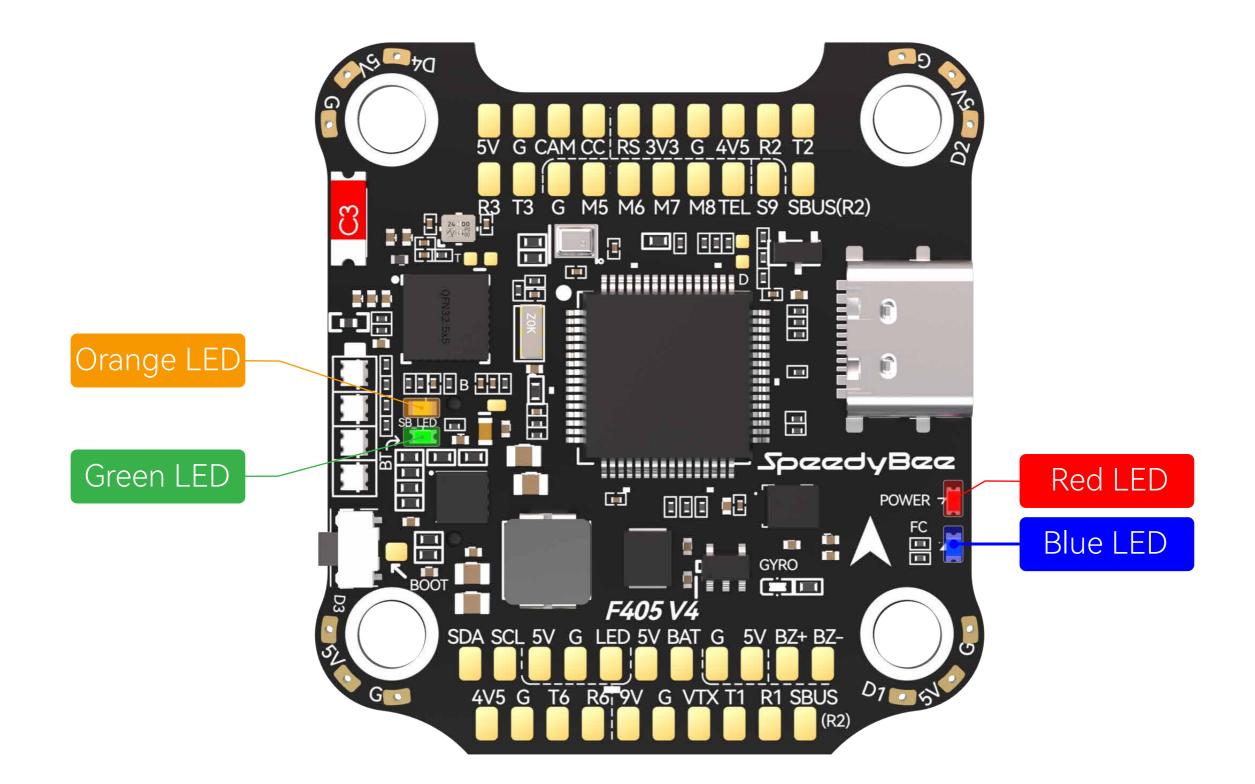


VTX(Analog)

VTX(DJI)



LED Indicator Definition



RED LED – Power Indicator.Solid Red after powering up.

GREEN LED – Bluetooth status light. Solid Green indicates Bluetooth is connected.

BLUE LED – Flight controller status light which is controlled by the flight controller firmware.
 Orange LED – LED Control Mode Indicator. It indicates the 4 sets of LED strips connected to LED1–LED4 pads on the corners of the flight controller are controlled by Betaflight firmware(BF_LED mode) or the Bluetooth chip(SB_LED mode).

Solid Orange : tindicates the 4 x LEDs are in SB_LED mode. In this mode, when the FC is powered on and in standby mode, press the BOOT button to cycle the display modes of the LEDs.

OFF : indicates the 4 x LEDs are controlled by Betaflight firmware. Long press the button for 3 seconds to switch the control modes between BF_LED mode and SB_LED mode.

BOOT Button

[A]Only if the flight controller gets bricked and can't power up, please follow these steps to re-flash firmware for it:

- ① Insert a USB A to TYPE-C cable to your PC.
- ② Press and hold the BOOT button, insert the USB cable into the flight controller, then release the BOOT button.
- ③ Open Betaflight/INAV configurator on the PC, go to the 'Firmware Flashing' page, choose the target 'SPEEDYBEEF405V4' and flash.

[B]. When the FC is powered on and in standby mode, the BOOT button can be used to control the LED strips connected to LED1-LED4 pads on the corners. Short-press the

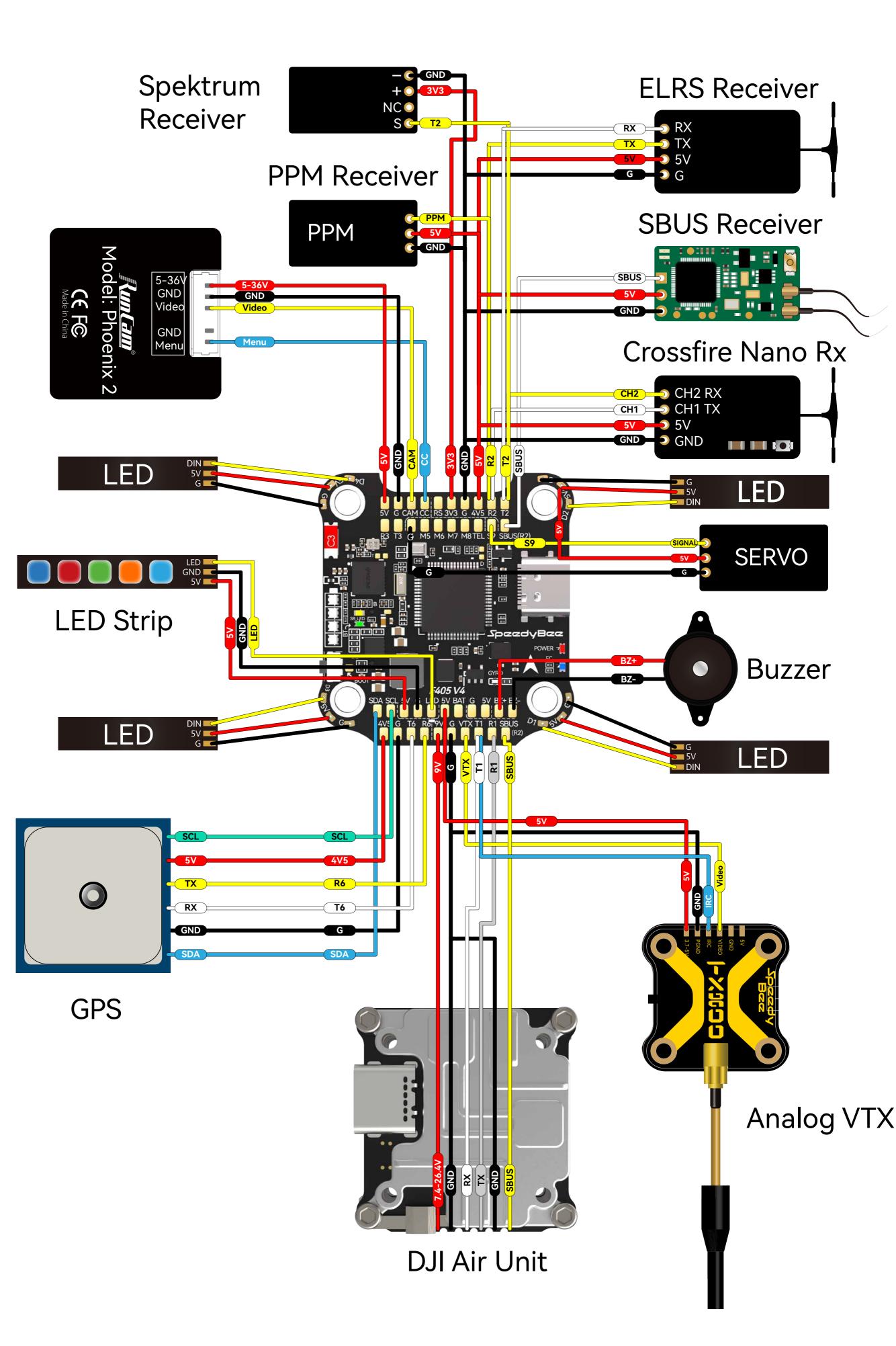
BOOT button to cycle the LED displaying mode. Long-press the BOOT button to switch

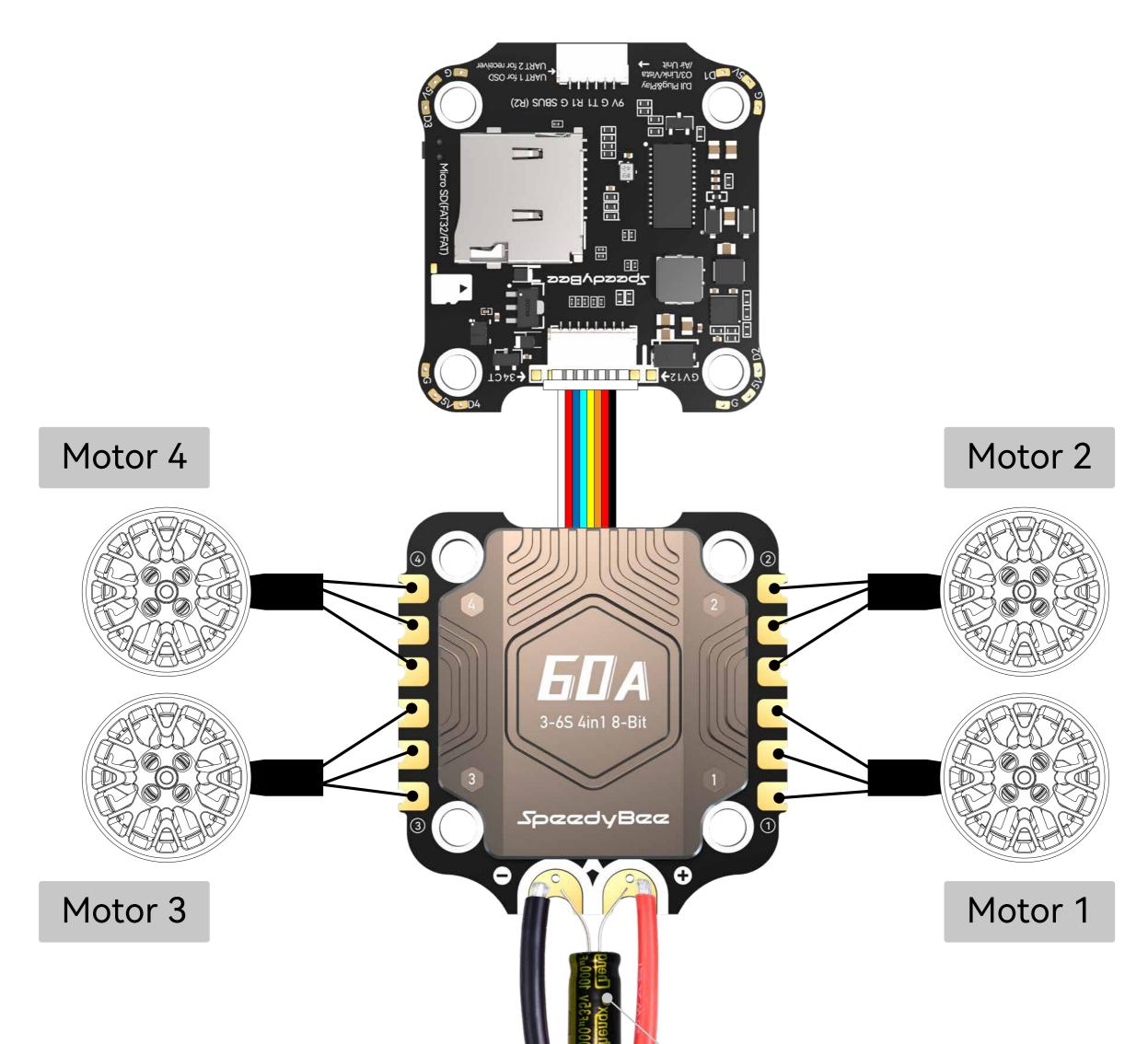
between SpeedyBee-LED mode and BF-LED mode. Under BF-LED mode,

all the LED1-LED4 strips will be controlled by the Betaflight firmware.

The default mode is BF-LED mode.

FC's Peripheral Connection

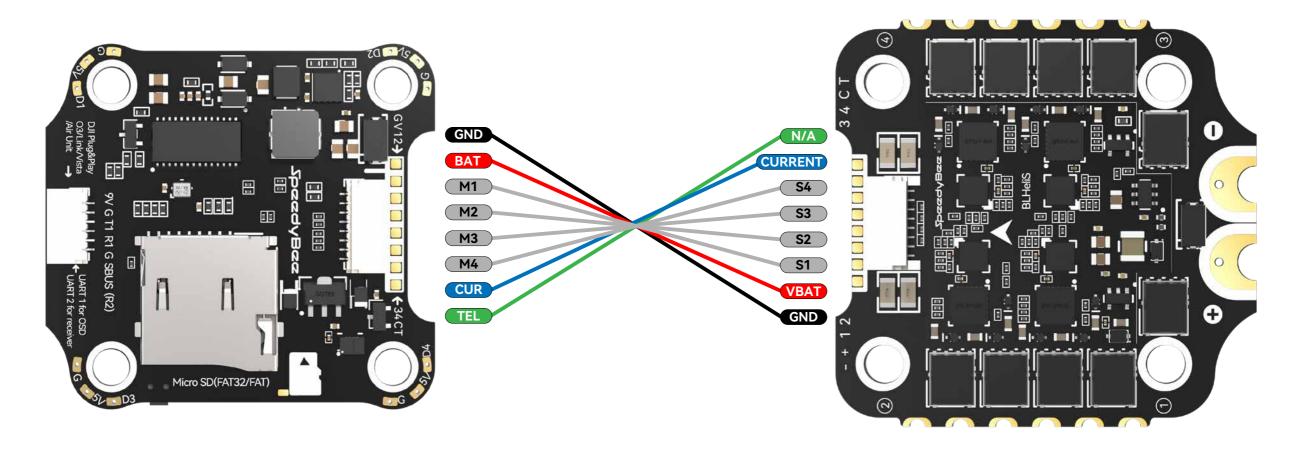






Note1: In order to prevent the stack from being burnt out by voltage spikes on powering up, it is strongly recommended to use the Low ESR capacitor in the package.

Note2: The FC and ESC can also connected via direct soldering. Soldering pads definition is as follows.



F405 V4 Flight Controller

BLS 60A 4-in-1 ESC

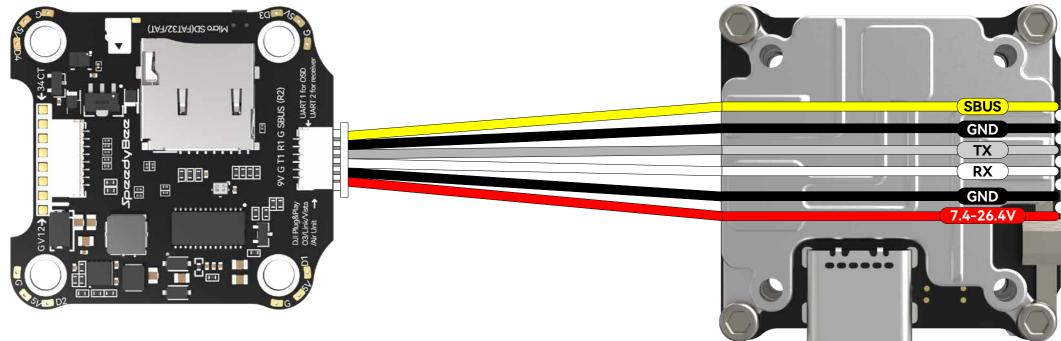
Cable Connection vs DJI O3 Air Unit

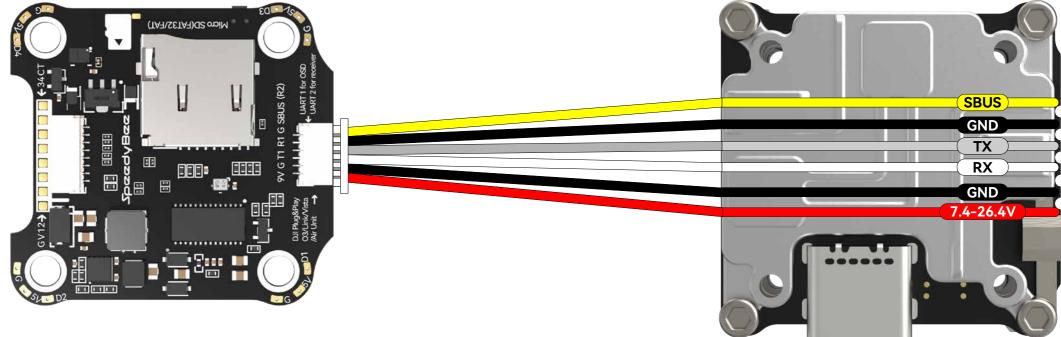
Use 6-pin cable comes with the O3 Air Unit



Cable Connection vs RunCam Link/ Caddx Vista Air Unit

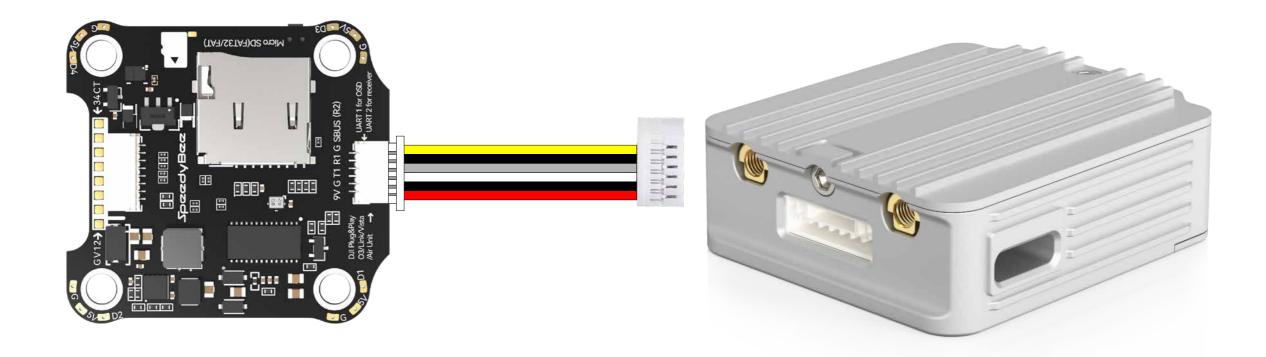
Use 6-pin cable comes with the F405 V4 stack (See the accessory No.11 in the package section)





Cable Connection vs DJI Air Unit V1

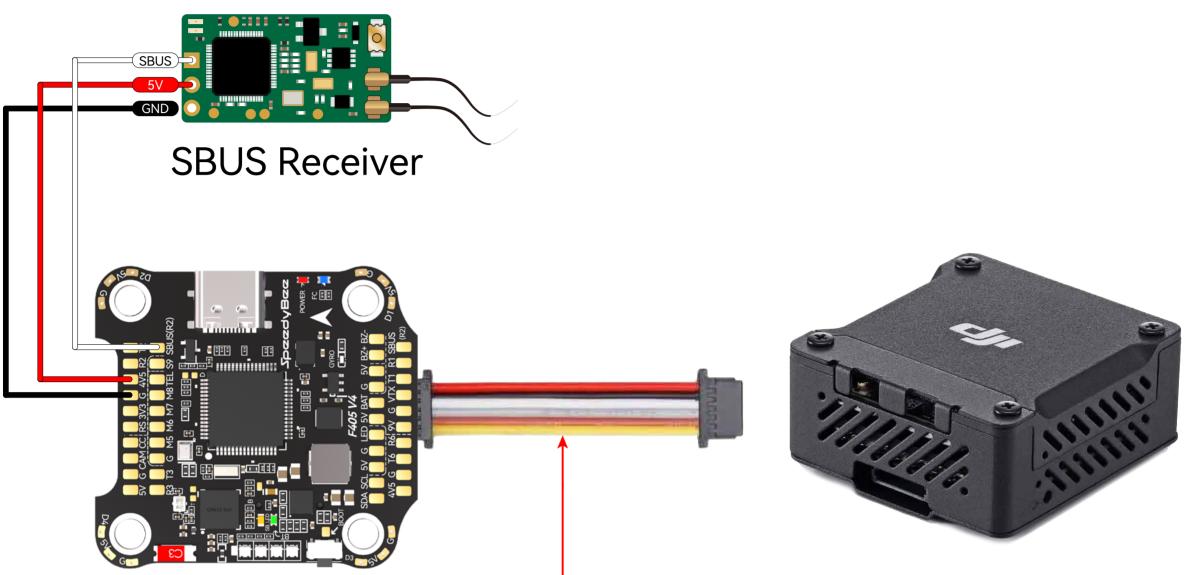
Use 6-pin cable comes with the F405 V4 stack (See the accessory No.11 in the package section)



Importance notice for SBUS receiver

When using an SBUS receiver, the SBUS signal wire of the receiver must be connected to the SBUS pad on the front side of the flight controller (this pad internally uses UART2).

If you are also using the DJI Air Unit(O3/Link/Vista/Air Unit V1), you will need to disconnect the SBUS signal wire from the Air Unit harness. Failure to do so will prevent the SBUS receiver from being properly recognized by the flight controller. You can use tweezers to pick out the SBUS wire from the 6-pin harness connector (or directly cut this wire) and insulate the exposed part of the wire carefully.



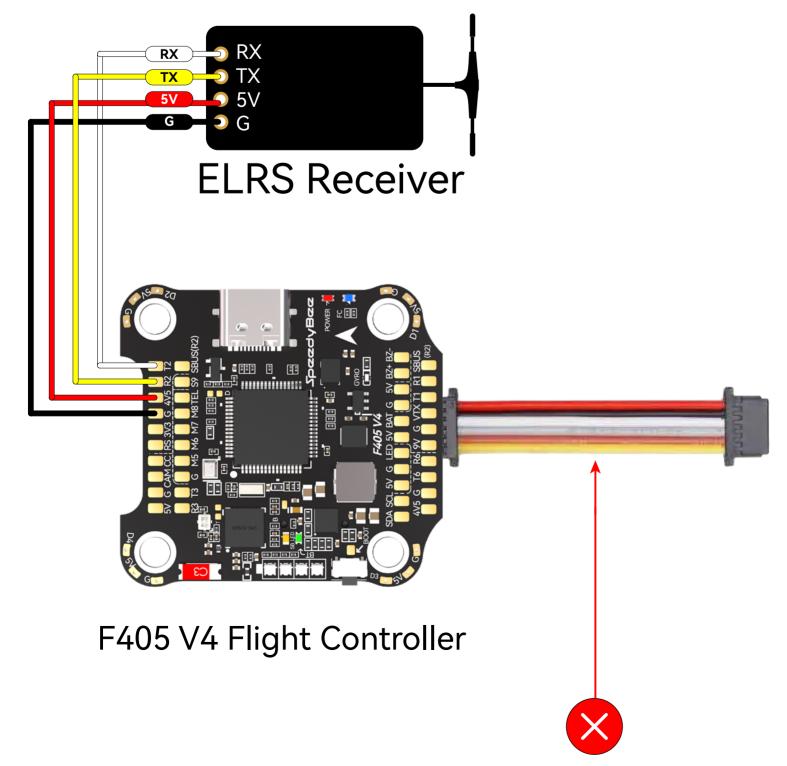
F405 V4 Flight Controller

DJI O3/Vista/Link/Air Unit V1

Do NOT connect this wire to assure the external SBUS receiver work properly!

Importance notice for ELRS receiver

We recommend connecting the ELRS receiver's TX and RX to the T2 and R2 pads on the flight controller. However, when using the DJI Air Unit simultaneously, some ELRS receivers may not be recognized properly by the flight controller. If you encounter this issue, you need to disconnect the SBUS signal wire from the Air Unit harness. You can use tweezers to pick out the SBUS wire from the 6-pin harness connector (or directly cut this wire) and insulate the exposed part of the wire carefully.





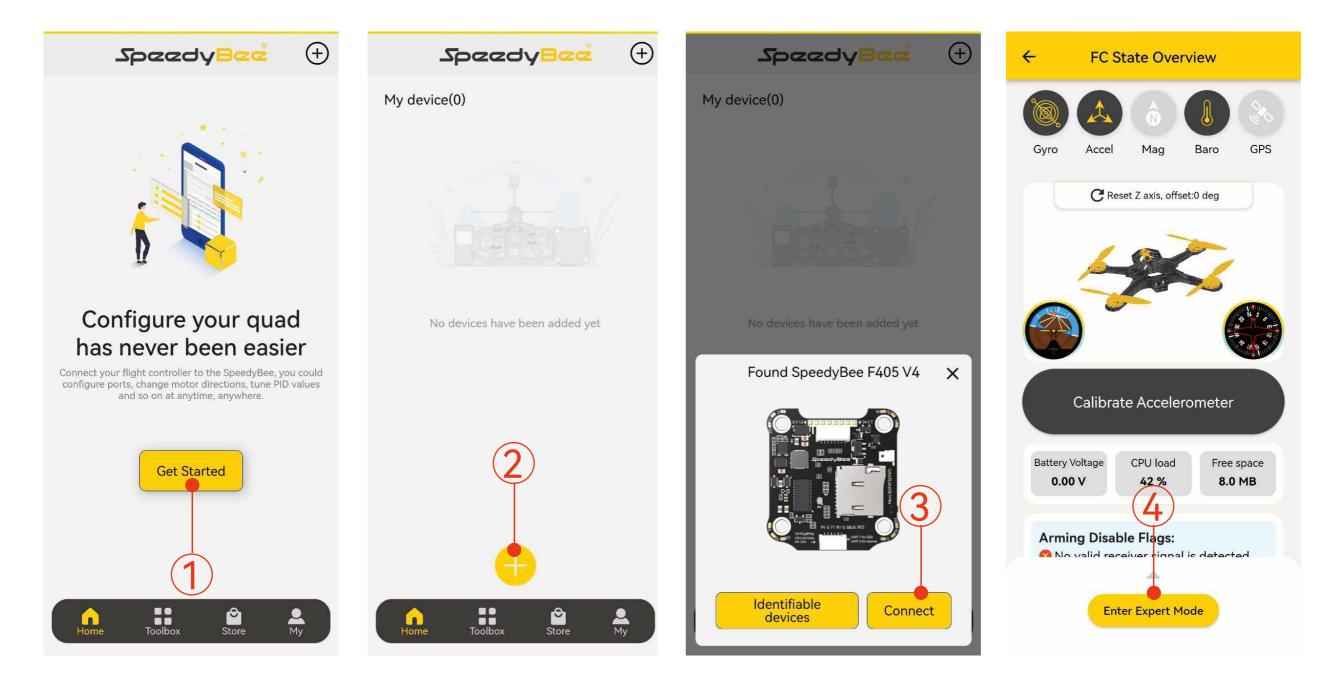
DJI O3/Vista/Link/Air Unit V1

For some ELRS receivers, it is necessary to disconnect this wire in order to function properly!

Get the SpeedyBee App

Search 'SpeedyBee' on Google Play or App Store. Or download the Android .apk file on our website: https://www.speedybee.com/download.

FC Configuration



FC Firmware Update

SpeedyBee F405 V4 flight controller does not support wireless firmware flashing, so please flash firmware for it on your PC following the steps below:

① Connect the flight controller to the PC with a USB cable

② Open Betafight/ INAV configurator on your PC. Take Betaflight

configurator as an example, go to the 'Firmware Flashing' page, choose the target '**SPEEDYBEEF405V4**' and flash.

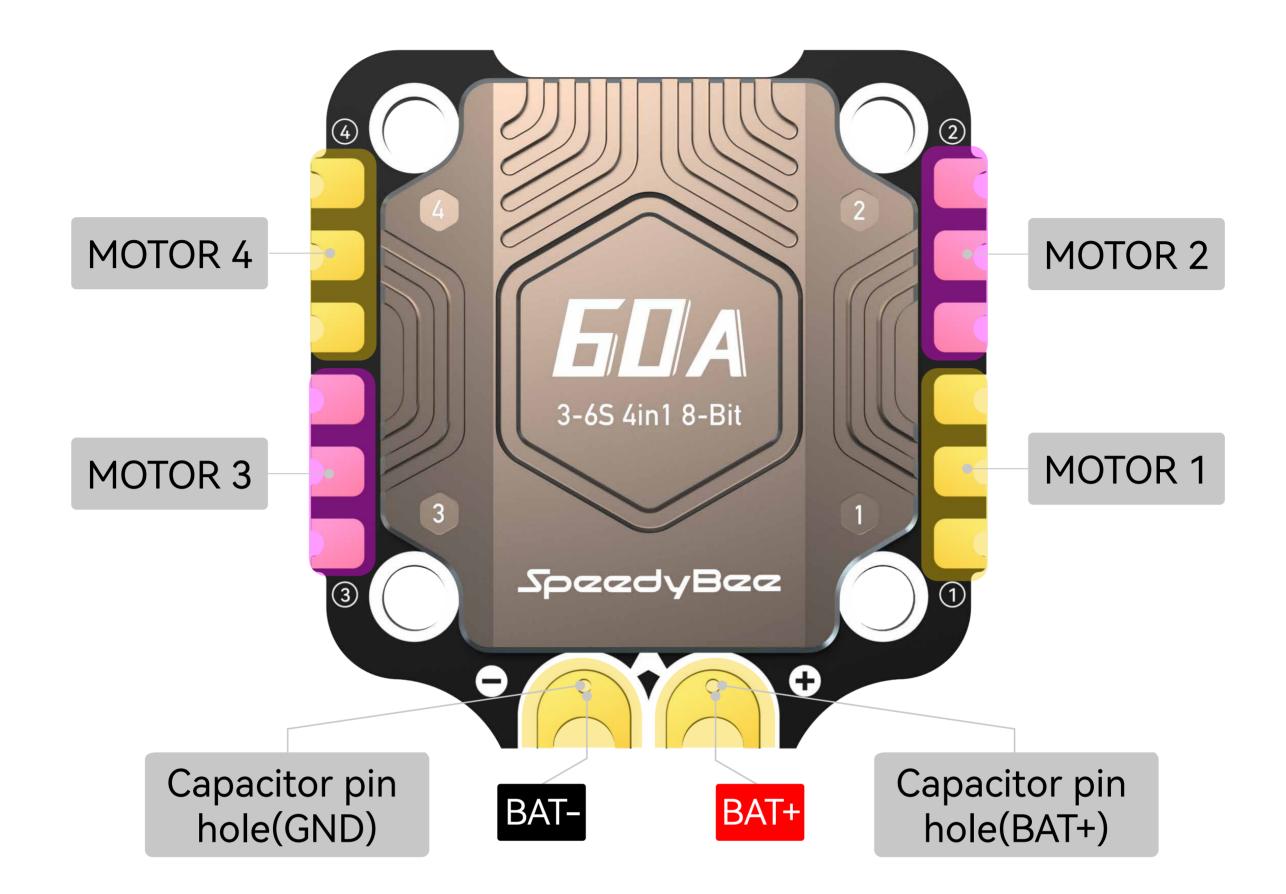
BETAFLIC Configurator: 10.9.0-del		COM6 - Betaflight STM32F405 Auto-Connect 115200 Update Firmware
2022-09-07 @11:56:25 Loaded builds 2022-09-07 @11:56:26 Loaded releas	ccessfully closed information for jobs from build server. information for jobs from build server. is information for firmware from GitHub. is information for firmware from GitHub.	Hide Log Scroll
🛸 Welcome		
🖪 Changelog	Show unstable releases	Show release candidates in addition to stable releases
🖪 Privacy Policy	Enable Expert Mode	Show unreleased and potentially unstable builds
Documentation & Support	Release Select build type to see available boards.	
Deptions	SPEEDYBEEF405V4	Auto-detect Select or auto-detect your board to see available online firmware releases - Select the correct firmware appropriate for your board.
📰 Firmware Flasher	13-07-2022 11:13 - 4.3.1	Select firmware version for your board.
	No reboot sequence	Enable if your FC is in boot mode. i.e. if you powered on your FC with the bootloader pins jumped or whilst holding your FC's BOOT button.
	Full chip erase	Wipes all configuration data currently stored on the board.
	Manual baud rate 256000 V	Manual selection of baud rate for boards that don't support the default speed or for flashing via bluetooth. Note: Not used when flashing via USB DFU
	Please load firmware file	Exit DFU Mode Flash Firmware Load Firmware [Online] Load Firmware [Local]
Port utilization: D: 0 % U: 0 % Packet	t error: 0 I2C error: 0 Cycle Time: 0 CPU Load:	0 % Configurator: 10.9.0-debug-ea02d9a

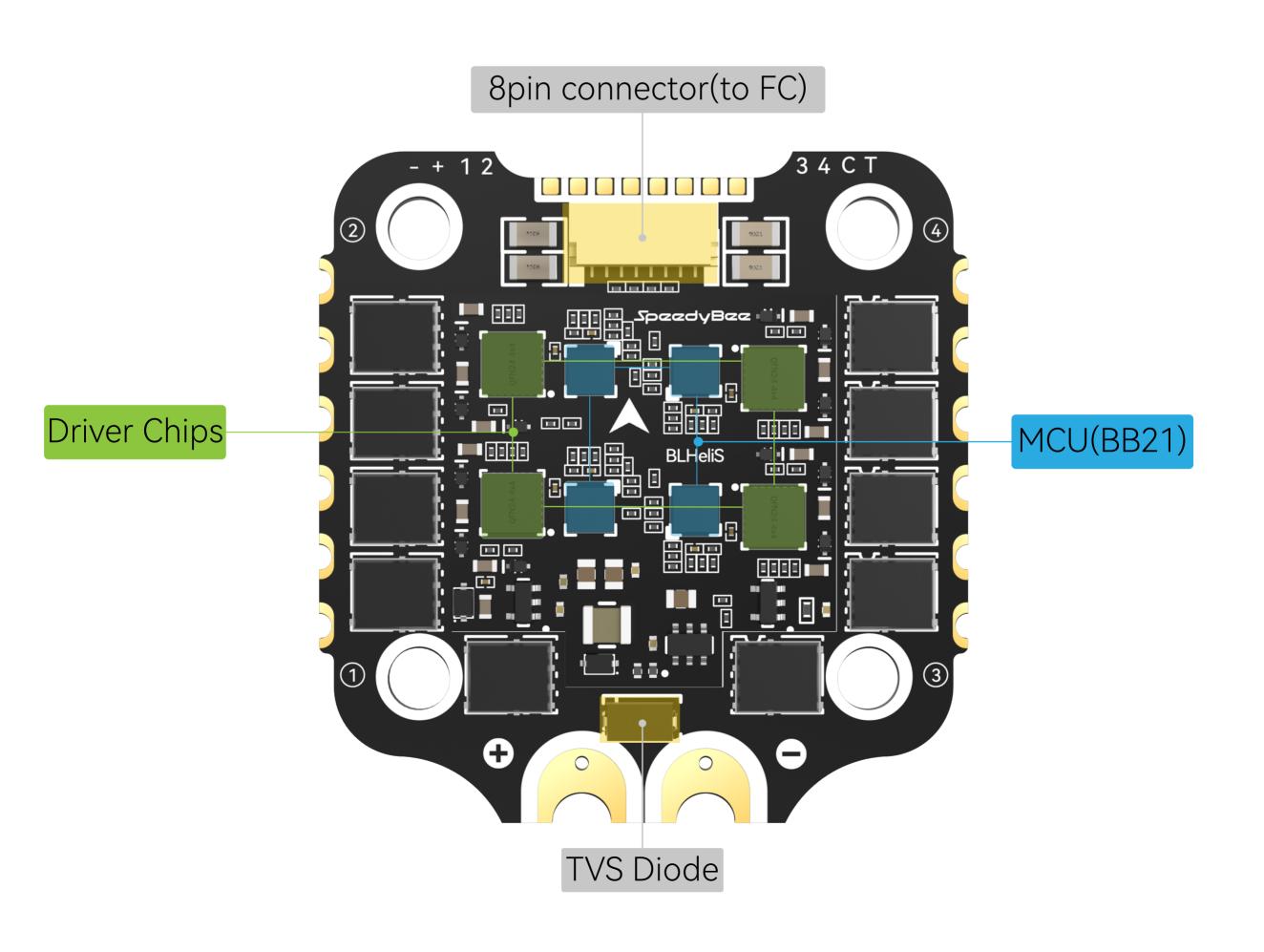
Product Name	SpeedyBee F405 V4 30x30 Flight Controller
MCU	STM32F405
IMU(Gyro)	ICM42688P
USB Port Type	Туре-С
Barometer	Built-in
OSD Chip	AT7456E chip
BLE Bluetooth	Supported. Used for Flight Controller configuration (MSP should be enabled with Baud rate 115200 on UART4)
WIFI	Not supported
DJI Air Unit Connection Way	Two ways supported: 6-pin connector or direct soldering.
6-pin DJI Air Unit Plug	Supported. Completely compatible with DJI O3/RunCam Link/Caddx Vista/DJI Air Unit V1, no wire is needed to be changed.
Blackbox MicroSD Card Slot	*Betaflight firmware requires the type of the microSD card to be either Standard (SDSC) or High capacity (SDHC) under 32GB, so extended capacity cards (SDXC) are not supported (Many high-speed U3 cards are SDXC). Also the microSD card MUST be formatted with the FAT16 or FAT32 (recommended) format. So, you could use any SD card less than 32GB, but the Betaflight can only recognize 4GB maximum. We suggest you use this <u>3rd party formatting</u> <u>tool</u> and choose 'Overwrite format' then format your card. Also check out <u>here</u> for the recommended SD cards or buy the <u>tested cards</u> from our store.
Current Sensor Input	Supported. For SpeedyBee BLS 60A ESC, please set scale = 400 and Offset = 0.
Power Input	3S - 6S Lipo(Through G, BAT pins/pads from the 8-pin connector or 8-pads on the bottom side)
5V Output	9 groups of 5V output, four +5V pads and 1 BZ+ pad(used for Buzzer) on front side, and 4x LED 5V pads. The total current load is 3A.
9V Output	2 groups of 9V output, one +9V pad on front side and other included in a connector on bottom side. The total current load is 3A.
3.3V Output	Supported. Designed for 3.3V-input receivers. Up to 500mA current load.
4.5V Output	Supported. Designed for receiver and GPS module even when the FC is powered through the USB port. Up to 1A current load.
ESC Signal	M1 - M4 on bottom side and M5-M8 on front side.
UART	6 sets(UART1, UART2, UART3, UART4(Dedicated for Bluetooth connection)), UART5 (Dedicated for ESC telemetry),UART6
ESC Telemetry	UART R5
I2C	Supported. SDA & SCL pads on front side. Used for magnetometer, sonar, etc.
Traditional Betaflight LED Pad	Supported. 5V, G and LED pads on bottom of the front side. Used for WS2812 LED controlled by Betaflight firmware.
Buzzer	BZ+ and BZ- pad used for 5V Buzzer
	Supported.
	[A]. Press and hold BOOT button and power the FC on at the same time will force the FC to enter DFU mode, this is for firmware flashing when the FC gets bricked.
BOOT Button	[B]. When the FC is powered on and in standby mode, the BOOT button can be used to controller the LED strips connected to LED1-LED4 connectors on the bottom side. By default, short-press the BOOT button to cycle the LED displaying mode. Long-press the BOOT button to switch between SpeedyBee-LED mode and BF-LED mode. Under BF-LED mode, all the LED1-LED4 strips will be controlled by Betaflight firmware.
RSSI Input	Supported. Named as RS on the front side.
Smart Port / F.Port	Not supported
Supported Flight Controller Firmware	BetaFlight(Default), INAV
Firmware Target Name	SPEEDYBEEF405V4
Mounting	30.5 x 30.5mm(4mm hole diameter)
Dimension	41.6(L) x 39.4(W) x 7.8(H)mm
Weight	10.5g

Part 3 – SpeedyBee BLS 60A 4-in-1 ESC

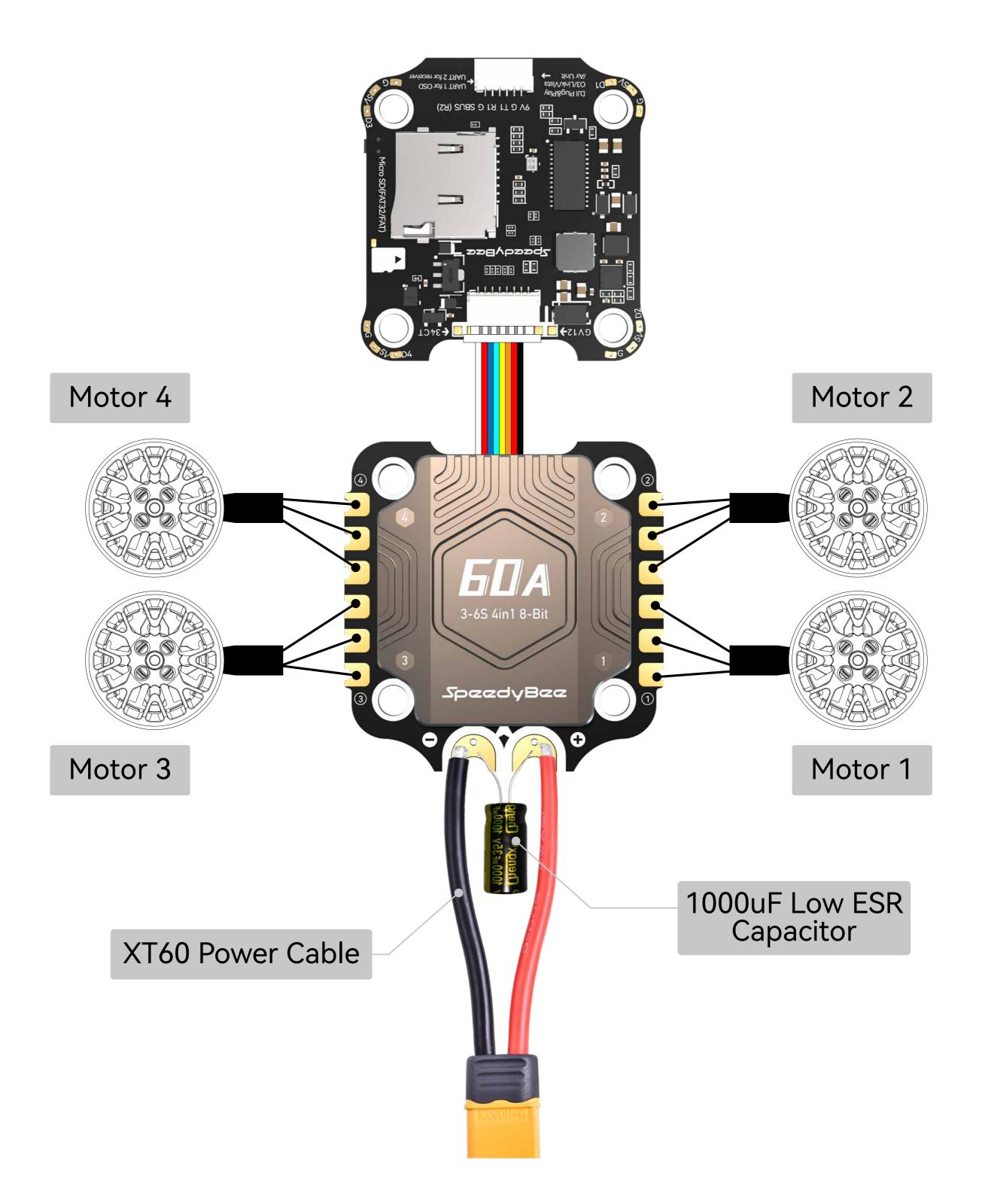
Layout

10/14



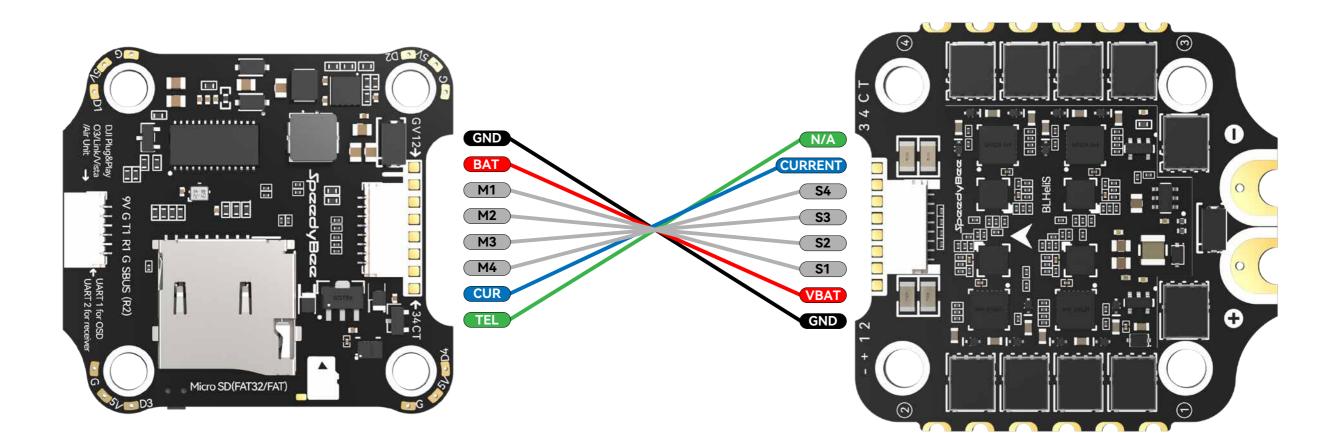


Connection with the flight controller & Motors 11/14



Note1: In order to prevent the stack from being burnt out by voltage spikes on powering up, it is strongly recommended to use the Low ESR capacitor in the package.

Note2: The FC and ESC can also connected via direct soldering. Soldering pads definition is as follows.

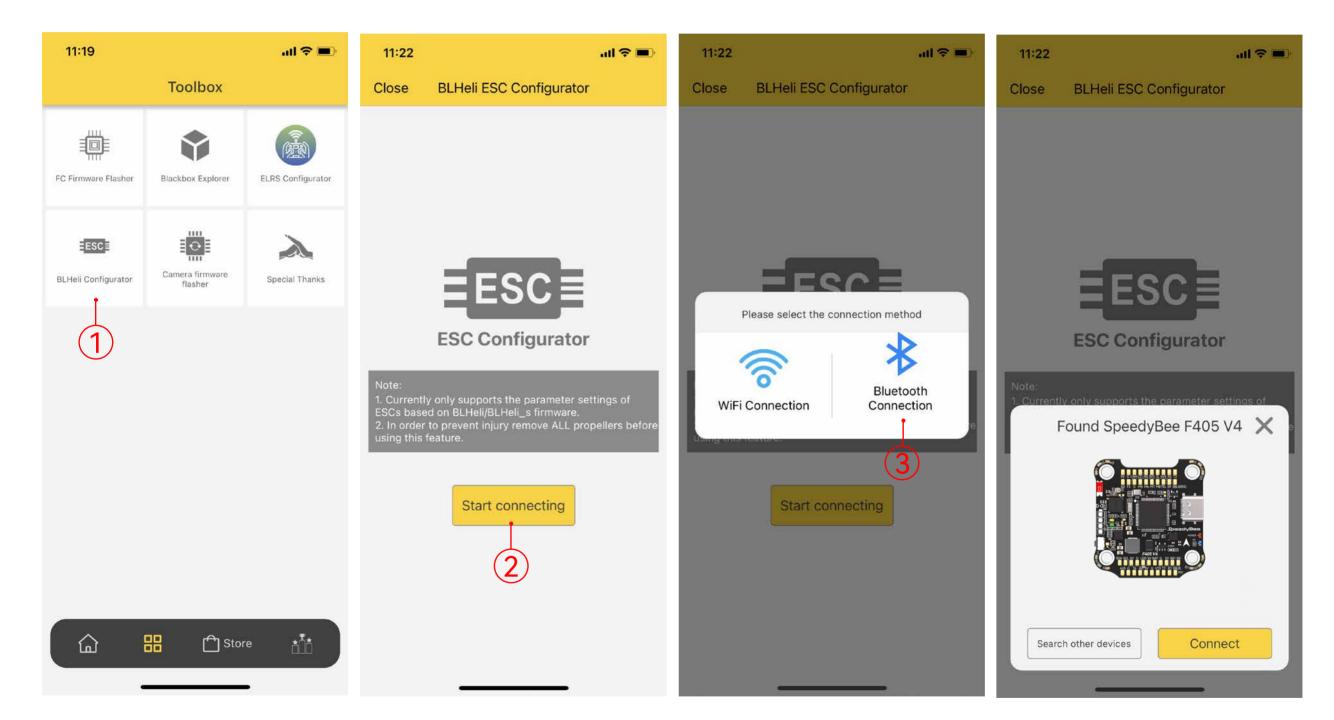


F405 V4 Flight Controller

BLS 60A 4-in-1 ESC

ESC Configuration

You could use the SpeedyBee APP to configure this ESC wirelessly for both BLHeli_S or Bluejay firmware. Steps:



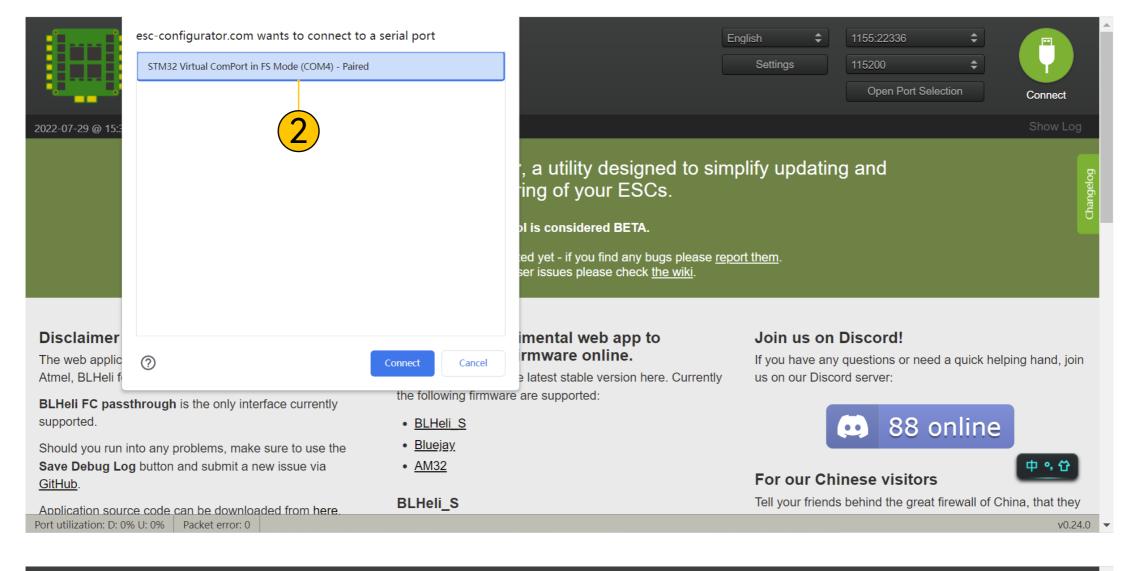
You could also use PC configurators to configure this ESC. We recommend the ESC Configurator. Please use Google Chrome browser and visist: <u>http://www.esc-configurator.com.</u> This 8-bit 60A ESC can run BLHeliS or Bluejay firmware. It is loaded with BLHeliS firmware by default. You could also flash it to Bluejay firmware which can support RPM filtering and Bi-directional Dhsot.

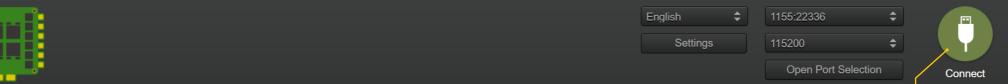
Firmware flashing steps are as follows:

- Remove all the propellers from your drone.
- Ensure that the flight controller is connected properly to the ESC, then power up the drone. This step ensures that the ESC starts up correctly.
- Connect the flight controller to the computer using a USB Type-C cable.
- Open the Chrome browser and visit the following website: <u>https://www.esc-configurator.com/</u>
- Follow the firmware flashing steps as shown in the screenshots below Important note:

On the 6th interface, the "ESC" type must be selected as "J-H-50".

Select Serial Port Settings 2022-07-29 @ 15:12:41 -- Chrome (103.0.0.0) on Windows Welcome to ESC - Configurator, a utility designed to simplify updating and configuring of your ESCs. This tool is considered BETA. Things might not work as expected yet - if you find any bugs please report them. For known browser issues please check the wiki Disclaimer Join us on Discord! This is an experimental web app to configure ESC firmware online. The web application supports ESCs running BLHeli for If you have any questions or need a quick helping hand, join Atmel, BLHeli for SiLabs and BLHeli_S. You will always find the latest stable version here. Currently us on our Discord server: the following firmware are supported: BLHeli FC passthrough is the only interface currently 86 online supported. • BLHeli S •• <u>Bluejay</u> Should you run into any problems, make sure to use the • <u>AM32</u> Save Debug Log button and submit a new issue via For our Chinese visitors GitHub. Tell your friends behind the great firewall of China, that they BLHeli_S Application source code can be downloaded from here. v0.24.0 -Port utilization: D: 0% U: 0% Packet error: 0





Welcome to **ESC - Configurator**, a utility designed to simplify updating and configuring of your ESCs.

This tool is considered BETA.

Things might not work as expected yet - if you find any bugs please <u>report them</u>. For known browser issues please check <u>the wiki</u>.

Disclaimer

The web application supports ESCs running BLHeli for Atmel, BLHeli for SiLabs and BLHeli_S.

BLHeli FC passthrough is the only interface currently supported.

Should you run into any problems, make sure to use the **Save Debug Log** button and submit a new issue via <u>GitHub</u>.

Application source code can be downloaded from here.

Port utilization: D: 0% U: 0% Packet error: 0

This is an experimental web app to configure ESC firmware online.

You will always find the latest stable version here. Currently the following firmware are supported:

- <u>BLHeli_S</u>
- <u>Bluejay</u>
- <u>AM32</u>

BLHeli_S

Join us on Discord!

If you have any questions or need a quick helping hand, join us on our Discord server:

3

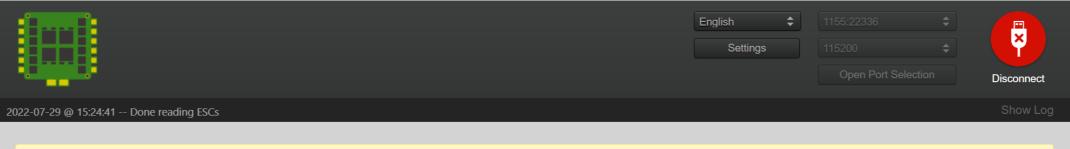


For our Chinese visitors

Tell your friends behind the great firewall of China, that they

v0.24.0 🔻

2022 07.29 @ 152427 Uhique device ID received - 0.004300423039510.35383236 Show Log Note: Make sure you're laken the propelles OFF before doing anything on this tab. Image: Connect power to the ESCs. Motor Control Make sure your ESCs are properly set up to reflect the state of the siders. Eg: When you enabled 3D mode in your light controller, make sure the ESCs are also set up for 3D mode, otherwise the motors will not spin if you have bi-directional Dabot enabled on the Flight-controller, but the ESC does not support it. Which might be the case when flashing from RPM enabled firmware to BitHeil (S.) Is beaware that the motors will not spin if you have bi-directional Dabot enabled on the Flight-controller, but the ESC does not support it. Which might be the case when flashing from RPM enabled firmware to BitHeil (S.) Is beaware that the motor will not spin if you have bi-directional Dabot enabled firmware to BitHeil (S.) Is beaware that the motor will not spin if you have bi-directional Dabot enabled firmware to BitHeil (S.) Is beable motor control Battery: 28 @ 7.16V Motor 1 Master Speed 1000 1000 1000 Sove Debug Log Clear Debug Log Read Retirugs Flash All ESC: Wite Settings Read Settings Sove Debug Log Decket error 0 Make set error 0 2020 Votettion (S.) Motor 2				English Settings	\$	1155:22336 115200 Open Por	¢ ¢ t Selection	Disconnect
Note: Connect power to the ESCs. Metor Control Make sure your ESCs are properly set up to reflect the state of the sliders. Eg: When you enabled 3D mode in your flight controller, make sure the ESCs are also set up for 3D mode, otherwise the motors might go of with full power. Also be aware that the motor smight go of with full power. Also be aware that the motor swill not spin if you have bi-directional Dshot enabled firmware to BLHeil_S. Enable motor control Battery: 25 @ 7.16V Motor 1 Master Speed 1000 1000 Motor 2 1000 1000 1000 Save Debug Log Clear Debug Log Restore Donfault Settings Plash All ESCs Write Settings Read Settings	2022-07-29 @ 15:24:27 Unique device I) received - 0x04300423039510c35383236						Show Log
Make sure your ESCs are properly set up to reflect the state of the sliders. Eg: When you enabled 3D mode in your flight controller, make sure the ESCs are also set up for 3D mode, otherwise the motors might go off with full power. Also be aware that the motors will not spin if you have bi-directional Dshot enabled on the Flight-controller, but the ESC does not support it. Which might be the case when flashing from RPM enabled firmware to BLHeirs. Enable motor control Battery: 25 @ 7.16V Motor 1 Master Speed 1000 1000 Motor 2 0 1000 1000 Save Debug Log Clear Debug Log Restore Default Settings Plash All ESCs Write Settings Read Settings		rs OFF before doing anything on this tab.						
Eg: When you enabled 3D mode in your flight controller, make sure the ESCs are also set up for 3D mode, otherwise the motors might go off with full power. Also be aware that the motors will not spin if you have bi-directional Dshot enabled on the Flight-controller, but the ESC does not support it. Which might be the case when flashing from RPM enabled firmware to BLHeli_S. Enable motor control Battery: 23 @ 7.16V Motor 1 Master Speed 1000 1000 Motor 2 0 1000 1000 Save Debug Log Clear Debug Log Read Settings	Motor Control							
otherwise the motors might go off with full power. Also be aware that the motors will not spin if you have bi-directional Dshot enabled on the Flight-controller, but the ESC does not support it. Which might be the case when flashing from RPM enabled firmware to BLHeli S. E nable motor control Battery: 2S @ 7.16V Motor 1 Master Speed 1000 Motor 2 Tool	Make sure your ESCs are properly set	up to reflect the state of the sliders.	-					
but the ESC does not support it. Which might be the case when flashing from RPM enabled firmware to BLHeli S. Enable motor control Battery: 25 @ 7.16V Motor 1 1000 Motor 2 1000 Save Debug Log Clear Debug Log Clear Debug Log Restore Default Settings Flash All ESCs Write Settings Read Settings	Eg.: When you enabled 3D mode in yo otherwise the motors might go off with	ur flight controller, make sure the ESCs are also set up for 3D mode, full power.						
Motor 1 1000 Motor 2 1000 Save Debug Log Clear Debug Log Clear Debug Log Restore Default Settings Flash All ESCs Write Settings Read Settings	but the ESC does not support it. Which	spin if you have bi-directional Dshot enabled on the Flight-controller, might be the case when flashing from RPM enabled firmware to						
1000 Motor 2 1000 Save Debug Log Clear Debug Log Clear Debug Log Restore Default Settings Flash All ESCs Write Settings Read Settings	Enable motor control	Battery: 2S @ 7.16V						
Motor 2 1000 Save Debug Log Clear Debug Log Restore Default Settings Flash All ESCs Write Settings Read Settings								
1000 Save Debug Log Clear Debug Log Restore Default Settings Flash All ESCs Write Settings	1000	1000						
Save Debug Log Clear Debug Log Flash All ESCs Write Settings Read Settings								4
Port utilization: D: 0% U: 0% Packet error: 0		og	Restore Default	Settings	Flash All	ESCs W	/rite Settings	Read Settings
	Port utilization: D: 0% U: 0% Packet erro	rr: 0						v0.24.0



Note: Make sure you've taken the propellers OFF before doing anything on this tab Note: Connect power to the ESCs.

Common Parameters		ESC 1: J-H-40 - BLHeli_S, 16.7
	Programming by TX	Reversed V Motor Direction ?
0.50	✓ Startup Power ?	1148 μs PPM Min Throttle
140 C	Temperature Protection Cow RPM Power Protection	1832 µs PPM Max Throttle
	Brake on stop ?	Off LED Configuration
Low	✓ Demag Compensation ?	Flash Firmware to this ESC
Medium 40	✓ Motor Timing ?	ESC 2: J-H-40 - BLHeli_S, 16.7
-•	Beep Strength ?	Reversed V Motor Direction ?
Save Debug Log	ear Debug Log	Restore Default Settings Flash All ESCs Write Settings Read Settings
Port utilization: D: 0% U: 0%	Packet error: 0	v0.24.0

		English ¢ Settings	1155/22336 \$ 115200 \$ Open Port Selection	Disconnect
2023-07-25 @ 10:07:04 Done reading ESCs				Show Log
directions and other settings yo the same firmware. Select Target (J-H-40 - BLI BLHeli_S J-H-40	ferent firmwares? are not migrated between different firmwares, make sur ou might want to move over. Settings will be migrated to Heli_S, 16.7) V Firmware ESC	re to take note of your motor between different versions of		
16.7 [Official]	Version Flash		4	
	Flash Local Firmware		9	
	Cancel			
	Cancer			

Specifications

Product Name	SpeedyBee BLS 60A 30x30 4-in-1 ESC
Firmware	BLHeli_S J-H-50
PC Configurator Download Link	https://esc-configurator.com/
Continuous Current	60A * 4
Burst Current	80A(10sec)
TVS Protective diode	Yes
External Capacitor	1000uF Low ESR Capacitor(In the package)
ESC Protocol	DSHOT300/600
Power Input	3-6S LiPo
Power Output	VBAT
Current Sensor	Support (Scale=400 Offset=0)
ESC Telemetry	Not supported
Mounting	30.5 x 30.5mm(4mm hole diameter)
Dimension	45.6(L) * 44(W) *8mm(H)
Weight	23.5g