## 1. General description

The HEF40106B provides six inverting buffers. Each input has a Schmitt trigger circuit. The inverting buffer switches at different points for positive-going and negative-going signals. The difference between the positive voltage ( $V_{T+}$ ) and the negative voltage ( $V_{T-}$ ) is defined as hysteresis voltage ( $V_H$ ).

The HEF40106B may be used for enhanced noise immunity or to "square up" slowly changing waveforms.

It operates over a recommended  $V_{DD}$  power supply range of 3 V to 15 V referenced to  $V_{SS}$  (usually ground). Unused inputs must be connected to  $V_{DD}$ ,  $V_{SS}$ , or another input.

### 2. Features and benefits

- Schmitt trigger input discrimination
- Fully static operation
- 5 V, 10 V, and 15 V parametric ratings
- Standardized symmetrical output characteristics
- Specified from –40 °C to +125 °C
- Complies with JEDEC standard JESD 13-B

### 3. Applications

- Wave and pulse shapers
- Astable multivibrators
- Monostable multivibrators

## 4. Ordering information

#### Table 1.Ordering information

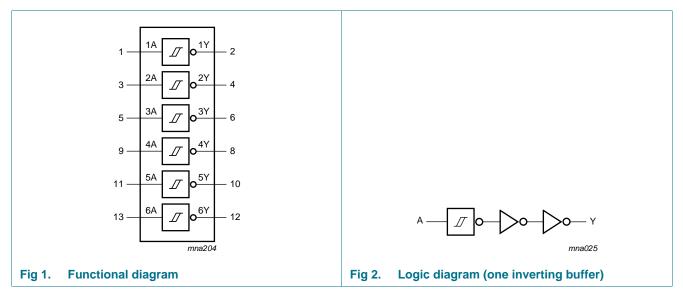
All types operate from -40 °C to +125 °C

Type number	Package	ge						
	Name	Description	Version					
HEF40106BP	DIP14	plastic dual in-line package; 14 leads (300 mil)	SOT27-1					
HEF40106BT	SO14	plastic small outline package; 14 leads; body width 3.9 mm	SOT108-1					
HEF40106BTT	TSSOP14	plastic thin shrink small outline package; 14 leads; body width 4.4 mm	SOT402-1					



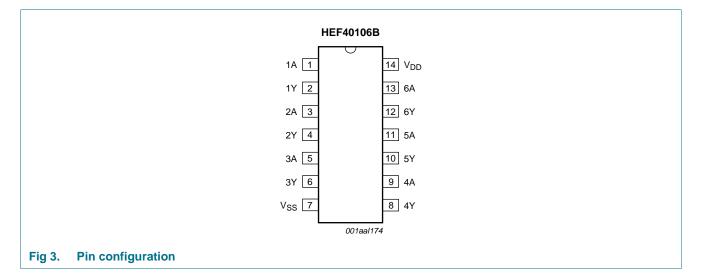
Hex inverting Schmitt trigger

# 5. Functional diagram



# 6. Pinning information

### 6.1 Pinning



### 6.2 Pin description

Table 2.	Pin description	
Symbol	Pin	Description
1A to 6A	1, 3, 5, 9, 11, 13	input
1Y to 6Y	2, 4, 6, 8, 10, 12	output
V <sub>DD</sub>	14	supply voltage
V <sub>SS</sub>	7	ground (0 V)

# 7. Functional description

Table 3.   Function table <sup>[1]</sup>	
Input	Output
nA	nY
L	Н
Н	L

[1] H = HIGH voltage level; L = LOW voltage level.

## 8. Limiting values

#### Table 4. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134). Voltages are referenced to  $V_{SS} = 0 V$  (ground).

				00 10	,
Symbol	Parameter	Conditions	Min	Max	Unit
$V_{DD}$	supply voltage		-0.5	+18	V
l <sub>IK</sub>	input clamping current	$V_{l}$ < -0.5 V or $V_{l}$ > $V_{DD}$ + 0.5 V	-	±10	mA
VI	input voltage		-0.5	$V_{DD}$ + 0.5	V
I <sub>OK</sub>	output clamping current	$V_{\rm O}$ < –0.5 V or $V_{\rm O}$ > $V_{\rm DD}$ + 0.5 V	-	±10	mA
I <sub>I/O</sub>	input/output current		-	±10	mA
I <sub>DD</sub>	supply current		-	50	mA
T <sub>stg</sub>	storage temperature		-65	+150	°C
T <sub>amb</sub>	ambient temperature		-40	+125	°C
P <sub>tot</sub>	total power dissipation	$T_{amb}$ = -40 °C to +125 °C			
		DIP14	<u>[1]</u> -	750	mW
		SO14	[2] _	500	mW
		TSSOP14	<u>[3]</u> _	500	mW
Р	power dissipation	per output	-	100	mW

[1] For DIP14 packages: above  $T_{amb}$  = 70 °C,  $P_{tot}$  derates linearly with 12 mW/K.

[2] For SO14 packages: above  $T_{amb}$  = 70 °C, P<sub>tot</sub> derates linearly with 8 mW/K.

[3] For TSSOP14 packages: above  $T_{amb} = 60 \degree C$ ,  $P_{tot}$  derates linearly with 5.5 mW/K.

# 9. Recommended operating conditions

Table 5.	Recommended operating conditions						
Symbol	Parameter	Conditions	Min	Max	Unit		
$V_{DD}$	supply voltage		3	15	V		
VI	input voltage		0	V <sub>DD</sub>	V		
T <sub>amb</sub>	ambient temperature	in free air	-40	+125	°C		

# **10. Static characteristics**

### Table 6. Static characteristics

 $V_{SS} = 0$  V;  $V_{I} = V_{SS}$  or  $V_{DD}$ ; unless otherwise specified.

Symbol	Parameter	Conditions	V <sub>DD</sub>	T <sub>amb</sub> =	–40 °C	T <sub>amb</sub> =	+25 °C	T <sub>amb</sub> =	+85 °C	T <sub>amb</sub> = -	⊦125 °C	Unit
				Min	Мах	Min	Max	Min	Max	Min	Max	
V <sub>OH</sub>	HIGH-level	I <sub>O</sub>   < 1 μA	5 V	4.95	-	4.95	-	4.95	-	4.95	-	V
	output voltage		10 V	9.95	-	9.95	-	9.95	-	9.95	-	V
			15 V	14.95	-	14.95	-	14.95	-	14.95	-	V
V <sub>OL</sub>	LOW-level	$ I_0  < 1 \ \mu A$	5 V	-	0.05	-	0.05	-	0.05	-	0.05	V
	output voltage		10 V	-	0.05	-	0.05	-	0.05	-	0.05	V
			15 V	-	0.05	-	0.05	-	0.05	-	0.05	V
I <sub>OH</sub>	HIGH-level	$V_{O} = 2.5 V$	5 V	-	-1.7	-	-1.4	-	-1.1	-	-1.1	mA
	output current	$V_{O} = 4.6 V$	5 V	-	-0.64	-	-0.5	-	-0.36	-	-0.36	mA
		$V_{O} = 9.5 V$	10 V	-	-1.6	-	-1.3	-	-0.9	-	-0.9	mA
		V <sub>O</sub> = 13.5 V	15 V	-	-4.2	-	-3.4	-	-2.4	-	-2.4	mA
I <sub>OL</sub>	LOW-level	$V_O = 0.4 V$	5 V	0.64	-	0.5	-	0.36	-	0.36	-	mA
	output current	$V_{O} = 0.5 V$	10 V	1.6	-	1.3	-	0.9	-	0.9	-	mA
		V <sub>O</sub> = 1.5 V	15 V	4.2	-	3.4	-	2.4	-	2.4	-	mA
lı	input leakage current		15 V	-	±0.1	-	±0.1	-	±1.0	-	±1.0	μA
I <sub>DD</sub>	supply current	all valid input	5 V	-	0.25	-	0.25	-	7.5	-	7.5	μΑ
		combinations;	10 V	-	0.5	-	0.5	-	15.0	-	15.0	μA
		I <sub>O</sub> = 0 A	15 V	-	1.0	-	1.0	-	30.0	-	30.0	μA
CI	input capacitance			-	-	-	7.5	-	-	-	-	pF

# **11. Dynamic characteristics**

#### Table 7. Dynamic characteristics

 $T_{amb} = 25 \degree C$ ;  $C_L = 50 \ pF$ ;  $t_r = t_f \le 20 \ ns$ ; wave forms see <u>Figure 4</u>; test circuit see <u>Figure 5</u>; unless otherwise specified.

<b>.</b>	-	•				_		
Symbol	Parameter	Conditions	V <sub>DD</sub>	Extrapolation formula <sup>[1]</sup>	Min	Тур	Мах	Unit
t <sub>PHL</sub>	HIGH to LOW	nA or nB to nY	5 V	63 ns + (0.55 ns/pF)C <sub>L</sub>	-	90	180	ns
	propagation delay		10 V	29 ns + (0.23 ns/pF)C <sub>L</sub>	-	35	70	ns
			15 V	22 ns + (0.16 ns/pF)C <sub>L</sub>	-	30	60	ns
t <sub>PLH</sub>	t <sub>PLH</sub> LOW to HIGH	nA or nB to nY	5 V	58 ns + (0.55 ns/pF)C <sub>L</sub>	-	75	150	ns
propagation delay		10 V	29 ns + (0.23 ns/pF)C <sub>L</sub>	-	35	70	ns	
			15 V	22 ns + (0.16 ns/pF)C <sub>L</sub>	-	30	60	ns
t <sub>THL</sub>	HIGH to LOW output	nY to LOW	5 V	10 ns + (1.00 ns/pF)C <sub>L</sub>	-	60	120	ns
	transition time		10 V	9 ns + (0.42 ns/pF)C <sub>L</sub>	-	30	60	ns
			15 V	6 ns + (0.28 ns/pF)C <sub>L</sub>	-	20	40	ns
t <sub>TLH</sub>	LOW to HIGH output	nA or nB to HIGH	5 V	10 ns + (1.00 ns/pF)C <sub>L</sub>	-	60	120	ns
	transition time		10 V	9 ns + (0.42 ns/pF)C <sub>L</sub>	-	30	60	ns
			15 V	6 ns + (0.28 ns/pF)C <sub>L</sub>	-	20	40	ns

[1] Typical value of the propagation delay and output transition time can be calculated with the extrapolation formula (C<sub>L</sub> in pF).

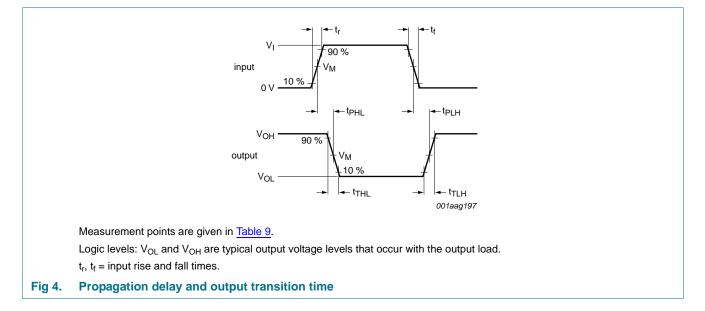
#### Table 8. Dynamic power dissipation

 $V_{SS} = 0 V$ ;  $t_r = t_f \le 20 ns$ ;  $T_{amb} = 25 \circ C$ .

Symbol	Parameter	$V_{DD}$	Typical formula	where:	
P <sub>D</sub> dynamic power		5 V	$P_D = 2300 \times f_i + \Sigma (f_o \times C_L) \times V_DD{}^2 \ (\muW)$	$f_i = input frequency in MHz;$	
	dissipation	10 V	$P_D = 9000 \times f_i + \Sigma (f_o \times C_L) \times V_DD{}^2 \; (\muW)$	$f_o = output frequency in MHz;$	
		15 V	$\textbf{P}_{D} = 20000 \times \textbf{f}_{i} + \Sigma(\textbf{f}_{o} \times \textbf{C}_{L}) \times \textbf{V}_{DD}^{2} \text{ (}\mu\textbf{W}\text{)}$	$C_L$ = output load capacitance in pF;	
				$\Sigma(f_o \times C_L)$ = sum of the outputs; V <sub>DD</sub> = supply voltage in V.	

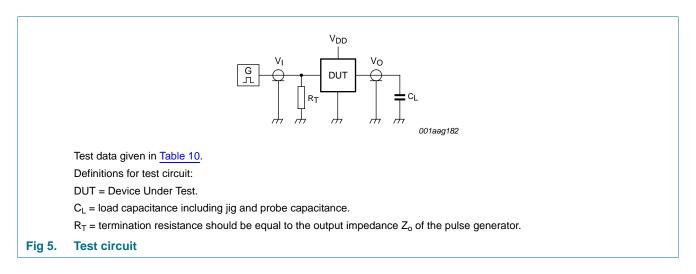
Hex inverting Schmitt trigger

### 12. Waveforms



#### Table 9. Measurement points

Supply voltage	Input	Output
V <sub>DD</sub>	V <sub>M</sub>	V <sub>M</sub>
5 V to 15 V	0.5V <sub>DD</sub>	0.5V <sub>DD</sub>



#### Table 10. Test data

Supply voltage	Input	Load	
V <sub>DD</sub>	VI	t <sub>r</sub> , t <sub>f</sub>	CL
5 V to 15 V	$V_{SS}$ or $V_{DD}$	$\leq$ 20 ns	50 pF

HEF40106B Product data sheet

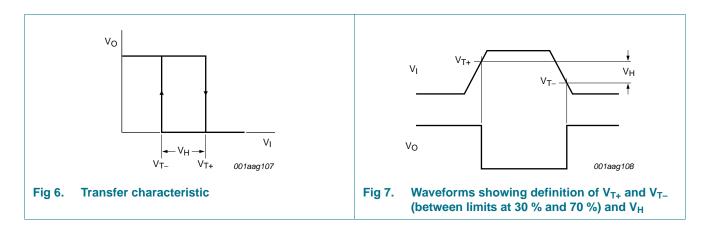
# **13. Transfer characteristics**

### Table 11.Transfer characteristics

 $V_{SS} = 0$  V; see <u>Figure 6</u> and <u>Figure 7</u>.

Symbol	Parameter	Conditions V <sub>DD</sub>		T <sub>amb</sub> = -40 °C to +85 °C			T <sub>amb</sub> = −40 °C to +125 °C		Unit
				Min	Typ <mark>[1]</mark>	Max	Min	Max	
$V_{T+}$	positive-going threshold voltage		5 V	2.0	3.0	3.5	2.0	3.5	V
			10 V	3.7	5.8	7.0	3.7	7.0	V
			15 V	4.9	8.3	11.0	4.9	11.0	V
V <sub>T-</sub>	negative-going threshold voltage		5 V	1.5	2.2	3.0	1.5	3.0	V
			10 V	3.0	4.5	6.3	3.0	6.3	V
			15 V	4.0	6.5	10.1	4.0	10.1	V
V <sub>H</sub>	hysteresis voltage		5 V	0.5	0.8	-	0.5	-	V
			10 V	0.7	1.3	-	0.7	-	V
			15 V	0.9	1.8	-	0.9	-	V

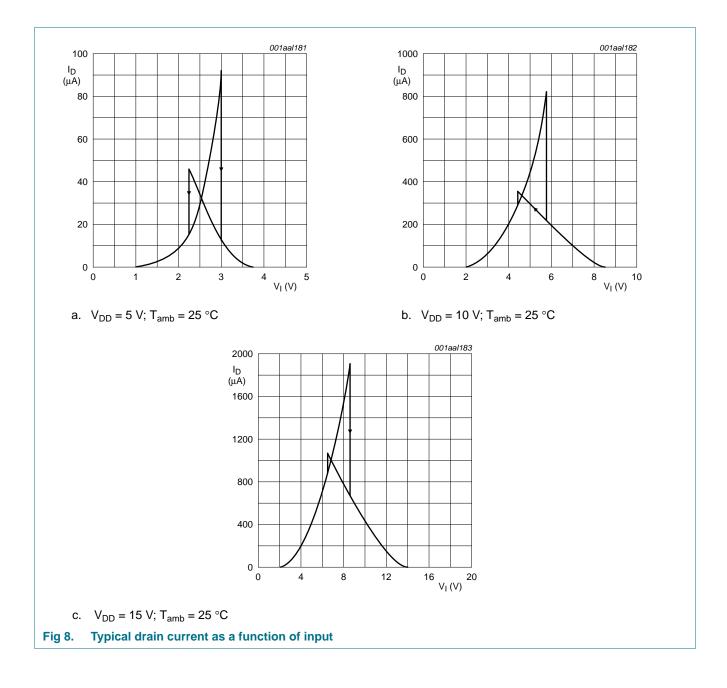
[1] All typical values are at  $T_{amb} = 25 \ ^{\circ}C$ .



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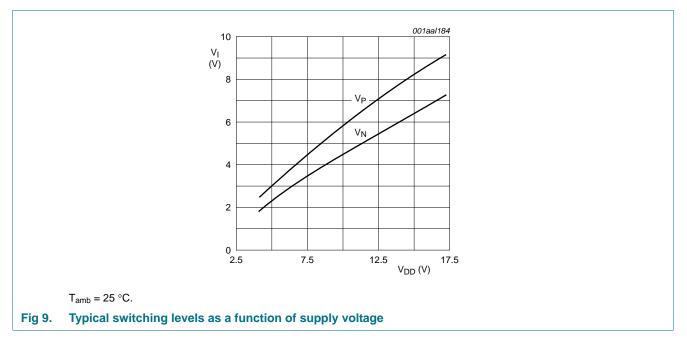
### Hex inverting Schmitt trigger



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# HEF40106B

### Hex inverting Schmitt trigger



## 14. Application information

Some examples of applications for the HEF40106B are:

- Wave and pulse shapers
- Astable multivibrators
- Monostable multivibrators



If a Schmitt trigger is driven via a high-impedance (R > 1 k $\Omega$ ), then it is necessary to

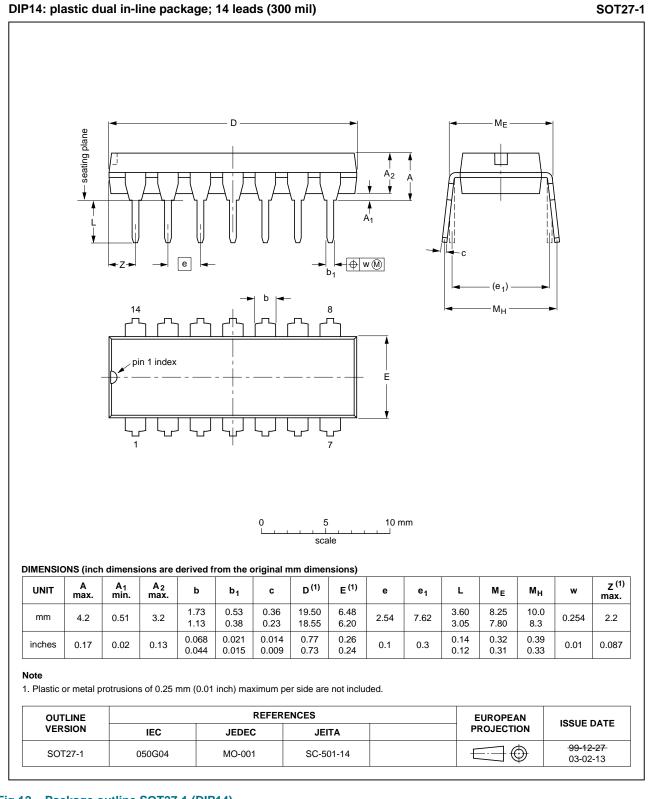
incorporate a capacitor C with a value of  $\frac{C}{C_P} > \frac{V_{DD} - V_{SS}}{V_H}$ ; otherwise oscillation can occur

on the edges of a pulse.

 $C_{\text{p}}$  is the external parasitic capacitance between inputs and output; the value depends on the circuit board layout.

Hex inverting Schmitt trigger

## 15. Package outline



### Fig 12. Package outline SOT27-1 (DIP14)

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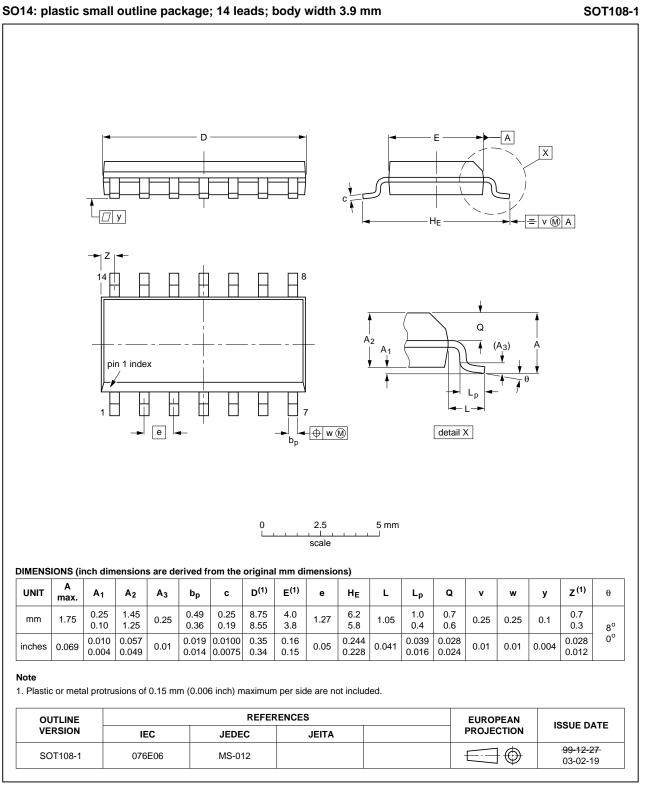
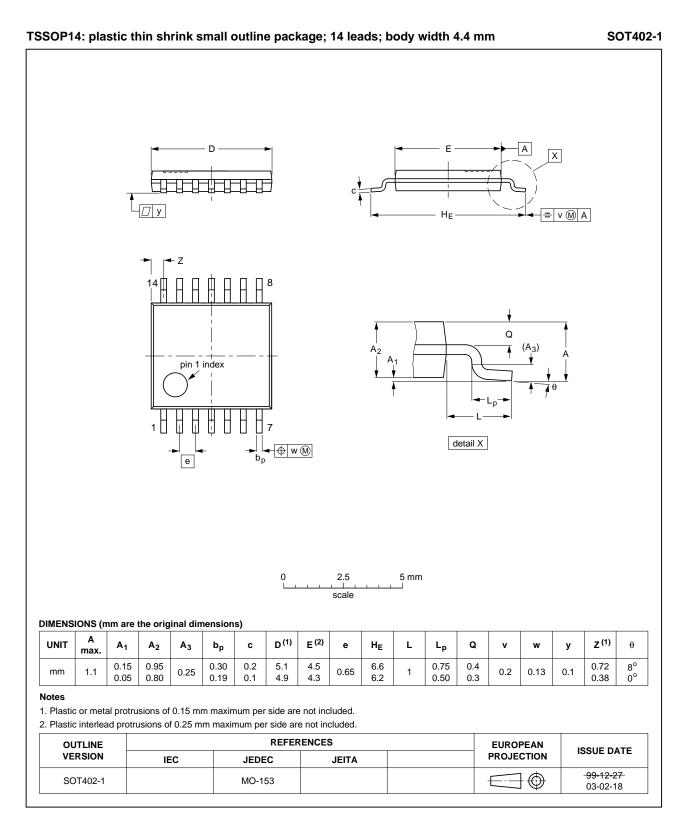


Fig 13. Package outline SOT108-1 (SO14)

HEF40106B



#### Fig 14. Package outline SOT402-1 (TSSOP14)

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HEF40106B

# 16. Revision history

Table 12. Revision his	story			
Document ID	Release date	Data sheet status	Change notice	Supersedes
HEF40106B v.7	20111121	Product data sheet	-	HEF40106B v.6
Modifications:	<ul> <li>Legal pages</li> </ul>	s updated.		
	<ul> <li>Changes in</li> </ul>	"General description" and "I	Features and benefits".	
HEF40106B v.6	20110823	Product data sheet	-	HEF40106B v.5
HEF40106B v.5	20110511	Product data sheet	-	HEF40106B v.4
HEF40106B v.4	20101115	Product data sheet	-	HEF40106B_CNV v.3
HEF40106B_CNV v.3	19950101	Product specification	-	HEF40106B_CNV v.2
HEF40106B_CNV v.2	19950101	Product specification	-	-

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# 17. Legal information

### 17.1 Data sheet status

Document status[1][2]	Product status <sup>[3]</sup>	Definition
Objective [short] data sheet	Development	This document contains data from the objective specification for product development.
Preliminary [short] data sheet	Qualification	This document contains data from the preliminary specification.
Product [short] data sheet	Production	This document contains the product specification.

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