

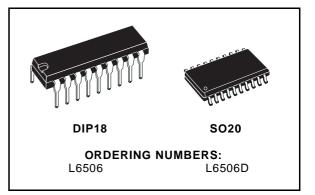
# L6506 L6506D

## CURRENT CONTROLLER FOR STEPPING MOTORS

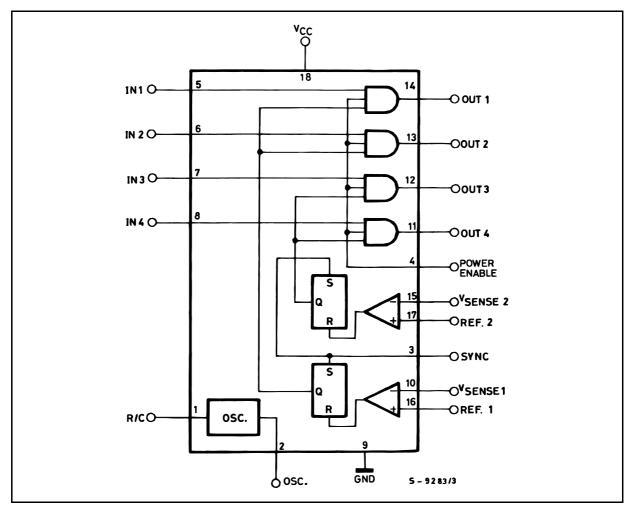
## DESCRIPTION

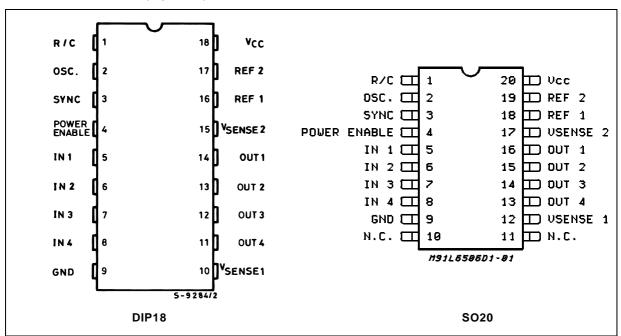
The L6506/D is a linear integrated circuit designed to sense and control the current in stepping motors and similar devices. When used in conjunction with the L293, L298, L7150, L6114/L6115, the chip set forms a constant current drive for an inductive load and performs all the interface function from the control logic thru the power stage.

Two or more devices may be synchronized using the sync pin. In this mode of operation the oscillator in the master chip sets the operating frequency in all chips.



## BLOCK DIAGRAM (pin's number referred to DIP-18)





## **PIN CONNECTIONS** (top view)

### **ABSOLUTE MAXIMUM RATINGS**

Symbol	Parameter	Value	Unit
Vcc	Supply Voltage	10	V
Vi	Input Signals	7	V
P <sub>tot</sub>	Total Power Dissipation ( $T_{amb} = 70^{\circ}C$ ) for DIP18 for SO20	1 0.8	W W
Tj	Junction Temperature	150	°C
T <sub>stg</sub>	Storage Temperature	-40 to 150	°C

## THERMAL DATA

Symbol	Parameter	DIP18	SO20	Unit
R <sub>th j-amb</sub>	Thermal Resistance Junction-ambient Max.	80	100	°C/W

#### **ELECTRICAL CHARACTERESTICS** (V<sub>CC</sub> = 5.0V, T<sub>amb</sub> = 25°C; unless otherwise noted)

Symbol	Parameter	Test Conditions	Min.	Тур.	Max.	Unit
V <sub>CC</sub>	Supply Voltage		4.5		7	V
Icc	Quiescent Supply Current	$V_{CC} = 7V$			25	mA

## **COMPARATOR SECTION**

Symbol	Parameter	Test Conditions	Min.	Тур.	Max.	Unit
VIN	Input Voltage Range	V <sub>sense</sub> Inputs	-0.3		3	V
V <sub>IO</sub>	Input Offset Voltage	$V_{IN} = 1.4V$			±5.0	mV
I <sub>IO</sub>	Input Offset Current				±200	nA
I <sub>IB</sub>	Input Bias Current				1	μA
	Response time	$V_{REF} = 1.4 V V_{SENS} = 0 \text{ to } 5 V$		0.8	1.5	μs



## ELECTRICAL CHARACTERISTICS (continued)

#### COMPARATOR SECTION PERFORMANCE (Over Operating Temperature Range)

Symbol	Parameter	Test Condtions	Min.	Тур.	Max.	Unit
V <sub>IO</sub>	Input Offset Voltage	$V_{IN} = 1.4V$			±20	mV
I <sub>IO</sub>	Input Offset Curent				±500	nA

LOGIC SECTION (Over Operating Temperature Range - TTL compatible inputs & outputs)

Symbol	Parameter	Test Condtions	Min.	Тур.	Max.	Unit
VIH	Input High Voltage		2		Vs	V
V <sub>IL</sub>	Input Low Voltage				0.8	V
V <sub>OH</sub>	Output High Voltage	V <sub>CC</sub> = 4.75V I <sub>OH</sub> = 400μA	2	3.5		V
V <sub>OL</sub>	Ouptut Low Voltage	V <sub>CC</sub> = 4.75V I <sub>OH</sub> = 4mA		0.25	0.4	V
I <sub>OH</sub>	Ouput Source Current - Outputs 1 - 4	$V_{CC} = 4.75V$	2.75			mA

#### OSCILLATOR

Symbol	Parameter	Test Condtions	Min.	Тур.	Max.	Unit
f <sub>osc</sub>	Frequency Range		5		70	KHz
V <sub>thL</sub>	Lower Threshold Voltage			0.33 V <sub>CC</sub>		V
V <sub>thH</sub>	Higher Threshold Voltage			0.66 V <sub>CC</sub>		V
Ri	Internal Discharge Resistor		0.7	1	1.3	kΩ

### **CIRCUIT OPERATION**

The L6506 is intended for use with dual bridge drivers, such as the L298, quad darlington arrays, such as the L7150, quad DMOS array such as L6114-L6115, or discrete power transistors to drive stepper motors and other similar loads. The main function of the device is to sense and control the current in each of the load windings.

A common on-chip oscillator drives the dual chopper and sets the operating frequency for the pulse width modulated drive. The RC network on pin 1 sets the operating frequency which is given by the equation .

$$f = \frac{1}{0.69 \text{ RC}} \text{ for } R > 10 \text{ K}$$

The oscillator provides pulses to set the two flipflops which in turn cause the outputs to activate the drive. When the current in the load winding reaches the programmed peak value, the voltage across the sense resistor ( $R_{sense}$ ) is equal to  $V_{ref}$  and the corresponding comparator resets its flip-flop interrupting the drive current until the next oscillator pulse occurs. The peak current in each winding is programmed by selecting the value of the sense resistor and V<sub>ref</sub>. Since separate inputs are provided for each chopper, each of the loads may be programmed independently allowing the device to be used to implement microstepping of the motor. Lower threshold of L6506's oscillator is 1/3 V<sub>CC</sub>. Upper threshold is 2/3 V<sub>CC</sub> and internal discharge resistor is 1 K $\Omega$  ± 30 %.

Ground noise problems in multiple configurations can be avoided by synchronizing the oscillators. This may be done by connecting the sync pins of each of the devices with the oscillator output of the master device and connecting the R/C pin of the unused oscillators to ground.

The equations for the active time of the sync pulse (T2), the inactive time of the sync signal (T1) and the duty cycle can be found by looking at the figure 1 and are :

T2 = 0.69 C1 
$$\frac{R1 R_{IN}}{R1 + R_{IN}}$$
 (1)

$$T1 = 0.69 R1 C1$$
 (2)

$$DC = \frac{I2}{T1 + T2}$$
(3)

By substituting equations 1 and 2 into equation 3 and solving for the value of R1 the following equations for the external components can be derived :

$$R1 = (\frac{1}{DC} - 2) R_{IN}$$
 (4)

$$C1 = \frac{T1}{0.69 \text{ R1}}$$
(5)

Figure 1 : Oscillator Circuit and Waveforms.

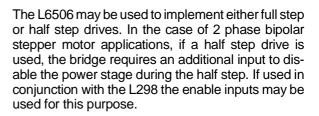
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#### **APPLICATIONS INFORMATION**

The circuits shown in figure 2 use the L6506 to implement constant current drives for stepper motors. Figure 2 shows the L6506 used with the L298 to drive a 2 phase bipolar motor. The peak current can be calculated using the equation :

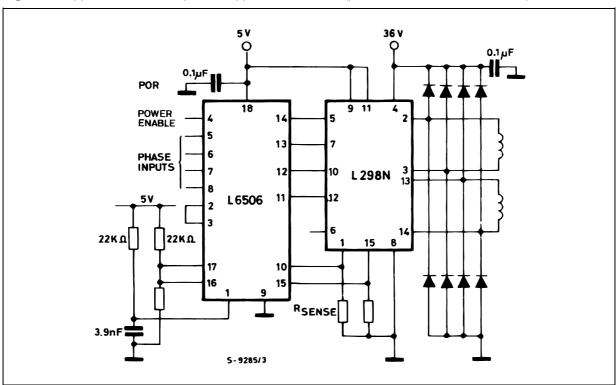
$$I_{peak} = \frac{V_{ref}}{R_{sense}}$$

The circuit of Fig.2 can be used in applications requiring different peak and hold current values by modifying the reference voltage. Looking at equation 1 it can easily be seen that the minimum pulse width of T2 will occur when the value of R1 is at its minimum and the value of R1 at its maximum. Therefore, when evaluating equation 4 the minimum value for R1 of  $700\Omega$  (1 K $\Omega$  – 30 %) should be used to guarantee the required pulse width.



For quad darlington array in 4 phase unipolar motor applications half step may be implemented using the 4 phase inputs.

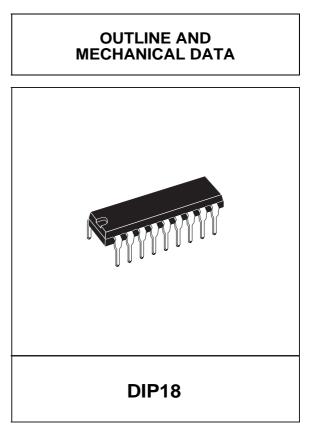
The L6506 may also be used to implement microstepping of either bipolar or unipolar motors.

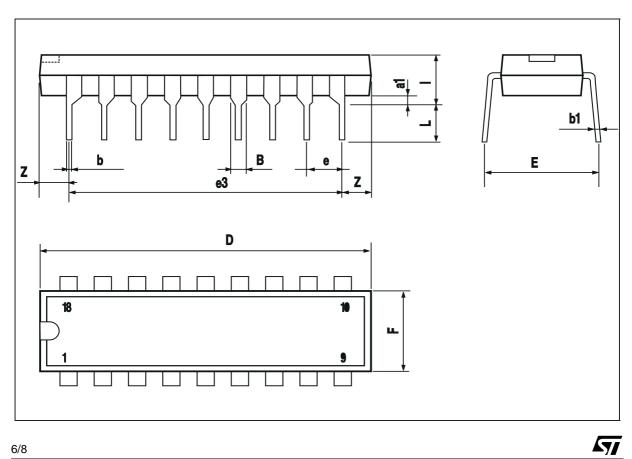




## L6506 -L6506D

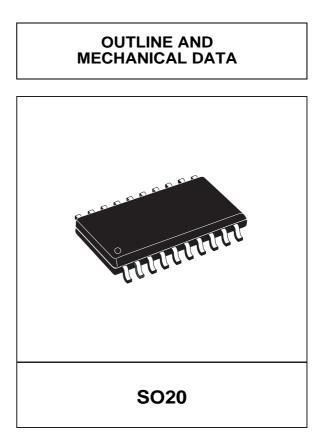
DIM.		mm			inch	
2	MIN.	TYP.	MAX.	MIN.	TYP.	MAX.
a1	0.254			0.010		
В	1.39		1.65	0.055		0.065
b		0.46			0.018	
b1		0.25			0.010	
D			23.24			0.915
E		8.5			0.335	
е		2.54			0.100	
e3		20.32			0.800	
F			7.1			0.280
I			3.93			0.155
L		3.3			0.130	
Z		1.27	1.59		0.050	0.063

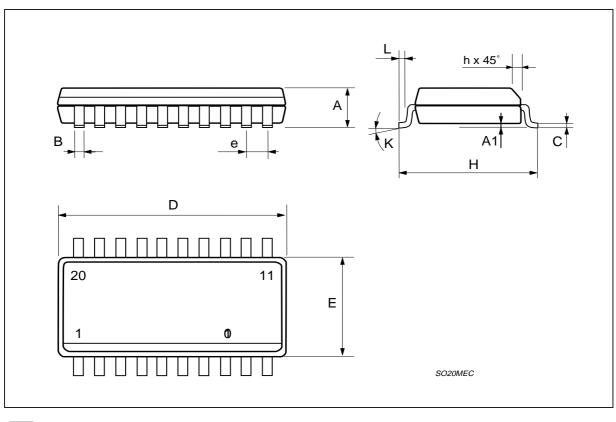




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DIM.		mm			inch		
	MIN.	TYP.	MAX.	MIN.	TYP.	MAX.	
А	2.35		2.65	0.093		0.104	
A1	0.1		0.3	0.004		0.012	
В	0.33		0.51	0.013		0.020	
с	0.23		0.32	0.009		0.013	
D	12.6		13	0.496		0.512	
E	7.4		7.6	0.291		0.299	
е		1.27			0.050		
н	10		10.65	0.394		0.419	
h	0.25		0.75	0.010		0.030	
L	0.4		1.27	0.016		0.050	
к	0° (min.)8° (max.)						





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