Microprocessor Supervisory Circuits

General Description

The MAX691A/MAX693A/MAX800L/MAX800M microprocessor (μ P) supervisory circuits are pin-compatible upgrades to the MAX691, MAX693, and MAX695. They improve performance with 30 μ A supply current, 200ms typ reset active delay on power-up, and 6ns chip-enable propagation delay. Features include write protection of CMOS RAM or EEPROM, separate watchdog outputs, backup-battery switchover, and a RESET output that is valid with V_{CC} down to 1V. The MAX691A/MAX800L have a 4.65V typical reset-threshold voltage, and the MAX693A/MAX800Ms' reset threshold is 4.4V typical. The MAX800L/MAX800M guarantee power-fail accuracies to ±2%.

Applications

- Computers
- Controllers
- Intelligent Instruments
- Critical µP Power Monitoring

Typical Operating Circuit



MaxCap is a registered trademark of Kanthal Globar, Inc.

Features

- 200ms Power-OK/Reset Timeout Period
- 1µA Standby Current, 30µA Operating Current
- On-Board Gating of Chip-Enable Signals, 10ns max Delay
- MaxCap® or SuperCap Compatible
- Guaranteed $\overline{\text{RESET}}$ Assertion to V_{CC} = +1V
- Voltage Monitor for Power-Fail or Low-Battery Warning
- Power-Fail Accuracy Guaranteed to ±2% (MAX800L/M)
- Available in 16-Pin Narrow SO, Plastic DIP, and TSSOP Packages

Ordering Information

PART	TEMP RANGE	PIN- PACKAGE
MAX691ACUE	-0°C to +70°C	16 TSSOP
MAX691ACSE	-0°C to +70°C	16 Narrow SO
MAX691ACWE	-0°C to +70°C	16 Wide SO
MAX691ACPE	-0°C to +70°C	16 Plastic DIP
MAX691AC/D	-0°C to +70°C	Dice*
MAX691AEUE	-0°C to +70°C	16 TSSOP
MAX691AESE	-40°C to +85°C	16 Narrow SO
MAX691AEWE	-40°C to +85°C	16 Wide SO
MAX691AEPE	-40°C to +85°C	16 Plastic DIP

Ordering Information continued at end of data sheet. *Dice are specified at $T_A = +25^{\circ}$ C, DC parameters only.

Devices in PDIP, SO, and TSSOP packages are available in both leaded and lead-free packaging. Specify lead free by adding the + symbol at the end of the part number when ordering. Lead free not available for CERDIP package.

Pin Configuration





Absolute Maximum Ratings

Terminal Voltage (with respect to GND)

V _{CC}	-0.3V to +6V
V _{VBATT}	0.3V to +6V
All Other Inputs	0.3V to (V _{OUT} + 0.3V)
Input Current	
V _{CC} Peak	1.0A
V _{CC} Continuous	250mA
VBATT Peak	250mA
VBATT Continuous	25mA
GND, BATT ON	100mA
All Other Outputs	25mA

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

Electrical Characteristics

(MAX691A, MAX800L: V_{CC} = +4.75V to +5.5V; MAX693A, MAX800M: V_{CC} = +4.5V to +5.5V; V_{VBATT} = 2.8V, T_A = T_{MIN} to T_{MAX} , unless otherwise noted.

PARAMETER	CONDITIONS			MIN	TYP	MAX	UNITS		
Operating Voltage Range, V _{CC} , V _{VBATT} (Note 1)					0		5.5	V	
		I _{OUT} =	I _{OUT} = 25mA		V _{CC} - 0.05	V _{CC} - 0.02			
				MAX69_AC	V _{CC} - 0.3	V _{CC} - 0.2		V	
V _{OUT} Output	V _{CC} = 4.5V	I _{OUT} =	250mA	MAX69_AE, MAX800_C/E	V _{CC} - 0.35	V _{CC} - 0.2			
				MAX69_A/M	V _{CC} - 0.40]	
		I _{OUT} =	210mA	MAX69_AC/AE, MAX800_C/E	V _{CC} - 0.3V	V _{CC} - 0.17			
		MAX69	9_AC, MAX	X800_C		0.8	1.2		
V _{CC} -to-V _{OUT} On-Resistance	V _{CC} = 4.5V	MAX69_AE, MAX800_E			0.8	1.4	Ω		
		MAX69	MAX69_A/M			0.8	1.6		
	V _{VBATT} = 4.5V, I _{OUT} = 20mA			V _{VBATT} - 0	.3		V		
V _{OUT} In Battery-Backup	V _{VBATT} = 2.8V, I _{OUT} = 10mA			V _{VBATT} - 0	.25				
	V _{VBATT} = 2.0V, I _{OUT} = 5mA			V _{VBATT} - 0	.15				
	V _{VBATT} = 4.5V					15			
On-Resistance	V _{VBATT} = 2.8V					25	Ω		
	V _{VBATT} = 2.0V						30		
Supply Current in Normal Operating Mode (excludes I _{OUT})	V _{CC} > V _{VBATT}	V _{CC} > V _{VBATT} - 1V			30	100	μΑ		
Supply Current in Battery-	V _{CC} < V _{VBATT} - 1.2V, V _{VBATT} = 2.8V		T _A = +25°0	C		0.04	1		
I _{OUT}) (Note 2)			$T_A = T_{MIN} + T_{MIN}$				5	μΑ	
VBATT Standby Current	V _{VBATT} + 0.2V	≤ 1	T _A = +25°0	0	-0.1		0.02		
(Note 3)	VCC		$T_A = T_{MIN} + T_{MIN}$		-1.0		0.02	μΑ	
Battery Switchover	Power-up	r-up		V _{VBATT} + 0.3			V		
Threshold	Power-down				V _{VBATT} - 0.3		v		

Microprocessor Supervisory Circuits

Electrical Characteristics (continued)

(MAX691A, MAX800L: V_{CC} = +4.75V to +5.5V; MAX693A, MAX800M: V_{CC} = +4.5V to +5.5V; V_{VBATT} = 2.8V, T_A = T_{MIN} to T_{MAX}, unless otherwise noted.

PARAMETER	CONDITIONS	MIN	ТҮР	MAX	UNITS	
Battery Switchover Hysteresis			60		mV	
BATT ON Output Low	I _{SINK} = 3.2mA		0.1	0.4	V	
Voltage	I _{SINK} = 25mA		0.7	1.5	V	
BATT ON Output	Sink current		60	100	mA	
Short-Circuit Current	Source current	1	15	100	μA	
RESET AND WATCHDOG TIMER						
	MAX691A, MAX800L	4.50	4.65	4.75		
Poset Threshold Voltage	MAX693A, MAX800M	4.25	4.40	4.50	V	
Reset miesnolu voltage	MAX800L, $T_A = +25^{\circ}C$, V_{CC} falling	4.55		4.70	v	
	MAX800M, $T_A = +25^{\circ}C$, V_{CC} falling	4.30		4.45		
Reset Threshold Hysteresis			15		mV	
V _{CC} to RESET Delay	Power-down		80		μs	
LOW LINE-to-RESET Delay			800		ns	
Reset Active Timeout Period, Internal Oscillator	Power-up	140	200	280	ms	
Reset Active Timeout Period, External Clock (Note 4)	Power-up		2048		Clock Cycles	
Watchdog Timeout Period,	Long period	1.0	1.6	2.25	sec	
Internal Oscillator	Short period	70	100	140	ms	
Watchdog Timeout Period,	Long period		4096		Clock	
External Clock (Note 4)	Short period		1024		Cycles	
Minimum Watchdog Input Pulse Width	V _{IL} = 0.8V, V _{IH} = 0.75 x V _{CC}	100			ns	
	$I_{SINK} = 50\mu A$, $V_{CC} = 1V$, VBATT = 0V, V_{CC} falling		0.004	0.3		
RESET Output Voltage	I _{SINK} = 3.2mA, V _{CC} = 4.25V		0.1	0.4	V	
	I _{SOURCE} = 1.6mA, V _{CC} = 5V	3.5				
RESET Output Short-Circuit Current	Output source current		7	20	mA	
RESET Output Voltage Low (Note 5)	I _{SINK} = 3.2mA	0.1	0.4		V	
	I _{SINK} = 3.2mA, V _{CC} = 4.25V			0.4	V	
LOW LINE Output voltage	$I_{SOURCE} = 1\mu A, V_{CC} = 5V$	3.5			7 V	
LOW LINE Output Short-Circuit Current	Output source current	1	15	100	μA	
	I _{SINK} = 3.2mA			0.4		
WDO Output Voltage	I _{SOURCE} = 500μA, V _{CC} = 5V	3.5				
WDO Output Short-Circuit Current	Output source current		3	10	mA	
WDI Threshold Voltage	V _{IH}	0.75 x V _{CC}				
(Note 6)	V _{IL}			0.8		
	WDI = 0V	-50	-10			
	WDI = V _{OUT}		20	50	μΑ	

Electrical Characteristics (continued)

(MAX691A, MAX800L: V_{CC} = +4.75V to +5.5V; MAX693A, MAX800M: V_{CC} = +4.5V to +5.5V; V_{VBATT} = 2.8V, T_A = T_{MIN} to T_{MAX}, unless otherwise noted.

PARAMETER	CONDITIONS	MIN	TYP	MAX	UNITS		
POWER-FAIL COMPARATOR							
DEL Input Throshold	MAX69_AC/AE/AM, $V_{CC} = 5V$	1.2	1.25	1.3	V		
PFI input Threshold	MAX800_C/E, $V_{CC} = 5V$	1.225	1.25	25 1.275			
PFI Leakage Current			±0.01	±25	nA		
	I _{SINK} = 3.2mA			0.4	V		
	$I_{SOURCE} = 1\mu A, V_{CC} = 5V$	3.5			v		
PFO Output Short-Circuit Current	Output source current	1	15	100	μΑ		
PEL to PEO Dolov	V _{IN} = -20mV, V _{OD} = 15mV		25		10		
PFI-10-PFO Delay	V _{IN} = 20mV, V _{OD} = 15mV		60		μs		
CHIP-ENABLE GATING							
CE IN Leakage Current	Disable mode		±0.005	±1	μA		
CE IN-to- CE OUT Resistance (Note 7)	Enable mode		75	150	Ω		
CE OUT Short-Circuit Current (Reset Active)	Disable mode, \overline{CE} OUT = 0V	0.1	0.75	2.0	mA		
CE IN-to- CE OUT Propagation Delay (Note 8)	50Ω source impedance driver, C_{LOAD} = 50pF		6	10	ns		
CE OUT Output-Voltage	V _{CC} = 5V, I _{OUT} = -100µA	3.5			V		
High (Reset Active)	V_{CC} = 0V, VBATT = 2.8V, I_{OUT} = 1 μ A	2.7			V		
RESET-to-CE OUT Delay	Power-down		12		μs		
INTERNAL OSCILLATOR							
OSC IN Leakage Current	OSC SEL = 0V		0.10	±5	μA		
OSC IN Input Pullup Current	OSC SEL = V _{OUT} or floating, OSC IN = 0V		10	100	μA		
OSC SEL Input Pullup Current	OSC SEL = 0V		10	100	μΑ		
OSC IN Frequency Range	OSC SEL = 0V		50		kHz		
OSC IN External Oscillator	VIH	V _{OUT} - 0.3	V _{OUT} - 0.6		- V		
i nresnoid voitage	VIL		3.65	2.00			
OSC IN Frequency with External Capacitor	OSC SEL = 0V, COSC = 47pF		100		kHz		

Note 1: Either V_{CC} or VBATT can go to 0V, if the other is greater than 2.0V.

Note 2: The supply current drawn by the MAX691A/MAX800L/MAX800M from the battery excluding I_{OUT} typically goes to 10μA when (VBATT - 1V) < V_{CC} < VBATT. In most applications, this is a brief period as V_{CC} falls through this region.
 Note 3: "+" = battery-discharging current, "--" = battery-charging current.

Note 4: Although presented as typical values, the number of clock cycles for the reset and watchdog timeout periods are fixed and do not vary with process or temperature.

Note 5: RESET is an open-drain output and sinks current only.

Note 6: WDI is internally connected to a voltage divider between V_{OUT} and GND. If unconnected, WDI is driven to 1.6V (typ), disabling the watchdog function.

Note 7: The chip-enable resistance is tested with V_{CC} = +4.75V for the MAX691A/MAX800L and V_{CC} = +4.5V for the MAX693A/MAX800M. \overline{CE} IN = \overline{CE} OUT = $V_{CC}/2$.

Note 8: The chip-enable propagation delay is measured from the 50% point at \overline{CE} IN to the 50% point at \overline{CE} OUT.

Typical Operating Characteristics

(TA = +25°C, unless otherwise noted.)



Microprocessor Supervisory Circuits

Typical Operating Characteristics (continued)

(TA = +25°C, unless otherwise noted.)



Microprocessor Supervisory Circuits

Pin Description

PIN	NAME	FUNCTION
1	VBATT	Battery-Backup Input. Connect to external battery or capacitor and charging circuit. If backup battery is not used, connect to GND.
2	V _{OUT}	Output Supply Voltage. When V _{CC} is greater than VBATT and above the reset threshold, V _{OUT} connects to V _{CC} . When V _{CC} falls below VBATT and is below the reset threshold, V _{OUT} connects to VBATT. Connect a 0.1µF capacitor from V _{OUT} to GND. Connect V _{OUT} to V _{CC} if no backup battery is used.
3	V _{CC}	Input Supply Voltage, 5V Input.
4	GND	Ground. 0V reference for all signals.
5	BATT ON	Battery-On Output. When V _{OUT} switches to VBATT, BATT ON goes high. When V _{OUT} switches to V _{CC,} BATT ON goes low. Connect the base of a PNP through a current-limiting resistor to BATT ON for V _{OUT} current require- ments greater than 250mA.
6	LOWLINE	$\overline{\text{LOW}}\overline{\text{LINE}}$ output goes low when V_{CC} falls below the reset threshold. It returns high as soon as V_{CC} rises above the reset threshold.
7	OSC IN	External Oscillator Input. When OSC SEL is unconnected or driven high, a 10 μ A pull-up connects from V _{OUT} to OSC IN, the internal oscillator sets the reset and watchdog timeout periods, and OSC IN selects between fast and slow watchdog timeout periods. When OSC SEL is driven low, the reset and watchdog timeout periods may be set either by a capacitor from OSC IN to ground or by an external clock at OSC IN (Figure 3).
8	OSC SEL	Oscillator Select. When OSC SEL is unconnected or driven high, the internal oscillator sets the reset delay and watchdog timeout period. When OSC SEL is low, the external oscillator input (OSC IN) is enabled (Table 1). OSC SEL has a 10µA internal pull-up.
9	PFI	Power-Fail Input. This is the noninverting input to the power-fail comparator. When PFI is less than 1.25V, PFO goes low. When PFI is not used, connect PFI to GND or V _{OUT} .
10	PFO	Power-Fail Output. This is the output of the power-fail comparator. PFO goes low when PFI is less than 1.25V. This is an uncommitted comparator, and has no effect on any other internal circuitry.
11	WDI	Watchdog Input. WDI is a three-level input. If WDI remains either high or low for longer than the watchdog time- out period, \overline{WDO} goes low and reset is asserted for the reset timeout period. \overline{WDO} remains low until the next tran- sition at WDI. Leaving WDI unconnected disables the watchdog function. WDI connects to an internal voltage divider between V _{OUT} and GND, which sets it to mid-supply when left unconnected.
12	CE OUT	Chip-Enable Output. \overline{CE} OUT goes low only when \overline{CE} IN is low and V_{CC} is above the reset threshold. If CE IN is low when reset is asserted, \overline{CE} OUT will stay low for 15µs or until \overline{CE} IN goes high, whichever occurs first.
13	CE IN	Chip-Enable Input. The input to chip-enable gating circuit. If \overline{CE} IN is not used, connect \overline{CE} IN to GND or V _{OUT.}
14	WDO	Watchdog Output. If WDI remains high or low longer than the watchdog timeout period, \overline{WDO} goes low and reset is asserted for the reset timeout period. \overline{WDO} returns high on the next transition at WDI. \overline{WDO} remains high if WDI is unconnected.
15	RESET	$\overrightarrow{\text{RESET}} \text{ Output goes low whenever } V_{CC} \text{ falls below the reset threshold. } \overrightarrow{\text{RESET}} \text{ will remain low typically for } 200 \text{ms after } V_{CC} \text{ crosses the reset threshold on power-up.} \\$
16	RESET	RESET is an active-high output. It is open drain, and the inverse of RESET.

Detailed Description

RESET and **RESET** Outputs

The MAX691A/MAX693A/MAX800L/MAX800M's RESET and RESET outputs ensure that the μ P (with reset inputs asserted either high or low) powers up in a known state, and prevents code-execution errors during power-down or brownout conditions.

The $\overline{\text{RESET}}$ output is active low, and typically sinks 3.2mA at 0.1V saturation voltage in its active state. When deasserted, $\overline{\text{RESET}}$ sources 1.6mA at typically V_{OUT} - 0.5V. RESET output is open drain, active high, and typically

sinks 3.2mA with a saturation voltage of 0.1V. When no backup battery is used, $\overline{\text{RESET}}$ output is guaranteed to be valid down to V_{CC} = 1V, and an external 10k Ω pulldown resistor on $\overline{\text{RESET}}$ insures that it will be valid with V_{CC} down to GND (Figure 1). As V_{CC} goes below 1V, the gate drive to the $\overline{\text{RESET}}$ output switch reduces accordingly, increasing the $R_{DS(ON)}$ and the saturation voltage. The 10k Ω pulldown resistor insures the parallel combination of switch plus resistor is around 10k Ω and the output saturation voltage is below 0.4V while sinking 40\muA. When using a 10k Ω external pulldown resistor, the high state for $\overline{\text{RESET}}$ output with V_{CC} = 4.75V will be 4.5V typical.

$\begin{array}{c} \hline RESET \\ MAX691A \\ MAX693A \\ \hline \hline \end{array} \\ \begin{array}{c} 15 \\ 1k\Omega \\ \hline \hline \end{array}$ TO µP RESET

Figure 1. Adding an external pulldown resistor ensures \overrightarrow{RESET} is valid with V_{CC} down to GND.

For battery voltages \ge 2V connected to VBATT, RESET and RESET remain valid for V_{CC} from 0V to 5.5V.

RESET and $\overrightarrow{\text{RESET}}$ are asserted when V_{CC} falls below the reset threshold (4.65V for the MAX691A/MAX800L, 4.4V for the MAX693A/MAX800M) and remain asserted for 200ms typ after V_{CC} rises above the reset threshold on power-up (Figure 5). The devices' batteryswitchover comparator does not affect reset assertion. However, both reset outputs are asserted in batterybackup mode since V_{CC} must be below the reset threshold to enter this mode.

Watchdog Function

The watchdog monitors μ P activity via the Watchdog Input (WDI). If the μ P becomes inactive, RESET and RESET are asserted. To use the watchdog function, connect WDI to a bus line or μ P I/O line. If WDI remains high or low for longer than the watchdog timeout period (1.6s nominal), WDO, RESET, and RESET are asserted (see RESET and RESET Outputs section, and the Watchdog Output discussion on this page).

Watchdog Input

A change of state (high to low, low to high, or a minimum 100ns pulse) at the WDI during the watchdog period resets the watchdog timer. The watchdog default timeout is 1.6s.

To disable the watchdog function, leave WDI floating. An internal resistor network ($100k\Omega$ equivalent impedance at WDI) biases WDI to approximately 1.6V. Internal comparators detect this level and disable the watchdog timer. When V_{CC} is below the reset threshold, the watchdog



Figure 2. Watchdog Timeout Period and Reset Active Time

function is disabled and WDI is disconnected from its internal resistor network, thus becoming high impedance.

Watchdog Output

The Watchdog Output (\overline{WDO}) remains high if there is a transition or pulse at WDI during the watchdog timeout period. The watchdog function is disabled and \overline{WDO} is a logic high when V_{CC} is below the reset threshold, battery-backup mode is enabled, or WDI is an open circuit. In watchdog mode, if no transition occurs at WDI during the watchdog timeout period, RESET and RESET are asserted for the reset timeout period (200ms typical). WDO goes low and remains low until the next transition at WDI (Figure 2). If WDI is held high or low indefinitely, RESET and RESET will generate 200ms pulses every 1.6s. WDO has a 2 x TTL output characteristic.

Selecting an Alternative Watchdog and Reset Timeout Period

The OSC SEL and OSC IN inputs control the watchdog and reset timeout periods. Floating OSC SEL and OSC IN or tying them both to V_{OUT} selects the nominal 1.6s watchdog timeout period and 200ms reset timeout period. Connecting OSC IN to GND and floating or connecting OSC SEL to V_{OUT} selects the 100ms normal watchdog timeout delay and 1.6s delay immediately after reset. The reset timeout delay remains 200ms (Figure 2). Select alternative timeout periods by connecting OSC SEL to GND and connecting a capacitor between OSC IN and GND, or by externally driving OSC IN (Table 1 and Figure 3). OSC IN is internally connected to a ±100nA (typ) current source that charges and discharges the timing capacitor to create the oscillator frequency, which sets the reset and watch-

Microprocessor Supervisory Circuits

MAX691A/MAX693A/ MAX800L/MAX800M

		WATCHD	RESET TIMEOUT	
USC SEL	USC IN	NORMAL	IMMEDIATELY AFTER RESET	PERIOD
Low	External Clock Input	1024 clks	4096 clks	2048 clks
Low	External Capacitor	(600/47pF x C)ms	(2.4/47pF x C)sec	(1200/47pF x C)ms
Floating	Low	100ms	1.6s	200ms
Floating	Floating	1.6s	1.6s	200ms

Table 1. Reset Pulse Width and Watchdog Timeout Selections



Figure 3. Oscillator Circuits

dog timeout periods (see Connecting a Timing Capacitor at OSC IN in the Applications Information section).

Chip-Enable Signal Gating

The MAX691A/MAX693A/MAX800L/MAX800M provide internal gating of chip-enable (CE) signals to prevent erroneous data from being written to CMOS RAM in the event of a power failure. During normal operation, the CE gate is enabled and passes all CE transitions. When reset is asserted, this path becomes disabled, preventing erroneous data from corrupting the CMOS RAM. All these parts use a series transmission gate from \overline{CE} IN to \overline{CE} OUT (Figure 4).

The 10ns max CE propagation delay from \overline{CE} IN to \overline{CE} OUT enables the parts to be used with most μ Ps.

Chip-Enable Input

The Chip-Enable Input (\overline{CE} IN) is high impedance (disabled mode) while RESET and \overline{RESET} are asserted.

During a power-down sequence where V_{CC} falls below the reset threshold or a watchdog fault, \overline{CE} IN assumes a high-impedance state when the voltage at \overline{CE} IN goes high or $15\mu s$ after reset is asserted, whichever occurs first (Figure 5).

During a power-up sequence, \overline{CE} IN remains high impedance, regardless of \overline{CE} IN activity, until reset is deasserted following the reset timeout period.

In the high-impedance mode, the leakage currents into this terminal are $\pm 1\mu A$ max over temperature. In the low-impedance mode, the impedance of \overline{CE} IN appears as a 75 Ω resistor in series with the load at \overline{CE} OUT.

The propagation delay through the CE transmission gate depends on both the source impedance of the drive to \overline{CE} IN and the capacitive loading on the Chip-Enable Output (\overline{CE} OUT) (see Chip-Enable Propagation Delay vs. \overline{CE} OUT Load Capacitance in the *Typical Operating Characteristics*). The CE propagation delay is production tested from the 50% point of \overline{CE} IN to the 50% point of \overline{CE} OUT using a 50 Ω driver and 50pF of load capacitance (Figure 6). For minimum propagation delay, minimize the capacitive load at \overline{CE} OUT, and use a low output-impedance driver.

Chip-Enable Output

In the enabled mode, the impedance of \overline{CE} OUT is equivalent to 75 Ω in series with the source driving \overline{CE} IN. In the disabled mode, the 75 Ω transmission gate is off and \overline{CE} OUT is actively pulled to V_{OUT}. This source turns off when the transmission gate is enabled.

LOW LINE Output

 $\label{eq:loss} \begin{array}{|c|c|c|c|c|} \hline LOW & \overline{LINE} \mbox{ is the buffered output of the reset threshold} \\ \hline comparator. & \overline{LOW} & \overline{LINE} \mbox{ typically sinks 3.2mA at 0.1V. For} \\ \hline normal operation (V_{CC} \mbox{ above the } \overline{LOW} & \overline{LINE} \mbox{ threshold}), \\ \hline LOW & \overline{LINE} \mbox{ is pulled to } V_{OUT}. \end{array}$

Power-Fail Comparator

The power-fail comparator is an uncommitted comparator that has no effect on the other functions of the IC. Common uses include low-battery indication (Figure 7), and early power-fail warning (see *Typical Operating Circuit*).

Microprocessor Supervisory Circuits



Figure 4. MAX691A/MAX693A/MAX800L/MAX800M Block Diagram



Figure 5. Reset and Chip-Enable Timing



Figure 6. CE Propagation Delay Test Circuit

Table 2. Input and Output Status inBattery-Backup Mode

PIN	NAME	STATUS
1	VBATT	Supply current is 1µA max.
2	V _{OUT}	V _{OUT} is connected to VBATT through an internal PMOS switch.
3	V _{CC}	Battery switchover comparator monitors V _{CC} for active switchover.
4	GND	GND 0V, 0V reference for all signals.
5	BATT ON	Logic high. The open-circuit output is equal to $V_{\mbox{OUT}}.$
6	LOWLINE	Logic low*
7	OSC IN	OSC IN is ignored.
8	OSC SEL	OSC SEL is ignored.
9	PFI	The power-fail comparator remains active in the battery-backup mode for $V_{CC} \ge VBATT - 1.2V$ typ.
10	PFO	The power-fail comparator remains active in the battery-backup mode for $V_{CC} \ge VBATT - 1.2V$ typ. Below this volt- age, PFO is forced low.
11	WDI	Watchdog is ignored.
12	CE OUT	Logic high. The open-circuit voltage is equal to V_{OUT} .
13	CE IN	High impedance
14	WDO	Logic high. The open-circuit voltage is equal to $V_{\mbox{OUT}}.$
15	RESET	Logic low*
16	RESET	High impedance*

 $^{*}V_{CC}$ must be below the reset threshold to enter battery-back-up mode.



Microprocessor Supervisory Circuits



Figure 7. Low-Battery Indicator

Power-Fail Input

Power-Fail Input (PFI) is the input to the power-fail comparator. It has a guaranteed input leakage of ±25nA max over temperature. The typical comparator delay is 25µs from V_{IL} to V_{OL} (power failing), and 60µs from V_{IH} to V_{OH} (power being restored). If PFI is not used, connect it to ground.

Power-Fail Output

The Power-Fail Output (\overline{PFO}) goes low when PFI goes below 1.25V. It typically sinks 3.2mA with a saturation voltage of 0.1V. With PFI above 1.25V, \overline{PFO} is actively pulled to V_{OUT}.

Battery-Backup Mode

Two conditions are required to switch to battery-backup mode: 1) V_{CC} must be below the reset threshold, and 2) V_{CC} must be below VBATT. Table 2 lists the status of the inputs and outputs in battery-backup mode.

Battery-On Output

The Battery-On (BATT ON) output indicates the status of the internal V_{CC}/battery-switchover comparator, which controls the internal V_{CC} and VBATT switches. For V_{CC} greater than VBATT (ignoring the small hysteresis effect), BATT ON typically sinks 3.2mA at 0.1V saturation voltage. In battery-backup mode, this terminal sources approximately 10µA from V_{OUT}. Use BATT ON to indicate battery-switchover status or to supply base drive to an external pass transistor for higher-current applications (see Typical Operating Circuit).

Input Supply Voltage

The Input Supply Voltage (V_{CC}) should be a regulated 5V. V_{CC} connects to V_{OUT} via a parallel diode and a large PMOS switch. The switch carries the entire cur-rent

Microprocessor Supervisory Circuits

load for currents less than 250mA. The parallel diode carries any current in excess of 250mA. Both the switch and the diode have impedances less than 1Ω each. The maximum continuous current is 250mA, but power-on transients may reach a maximum of 1A.

Battery-Backup Input

The Battery-Backup Input (VBATT) is similar to the V_{CC} input except the PMOS switch and parallel diode are much smaller. Accordingly, the on-resistances of the diode and the switch are each approximately 10 Ω . Continuous current should be limited to 25mA and peak currents (only during power-up) limited to 250mA. The reverse leakage of this input is less than 1µA over temperature and supply voltage (Figure 8).

Output Supply Voltage

The Output Supply Voltage (V_{OUT}) pin is internally connected to the substrate of the IC and supplies current to the external system and internal circuitry. All opencircuit outputs will, for example, assume the V_{OUT} voltage in their high states rather than the V_{CC} voltage. At the maximum source current of 250mA, V_{OUT} will typically be 200mV below V_{CC}. Decouple this terminal with a 0.1µF capacitor.

Applications Information

The MAX691A/MAX693A/MAX800L/MAX800M are not short-circuit protected. Shorting V_{OUT} to ground, other than power-up transients such as charging a decoupling capacitor, destroys the device.

All open-circuit outputs swing between V_{OUT} and GND rather than V_{CC} and GND.



Figure 8. V_{CC} and VBATT to VOUT Switch

If long leads connect to the chip inputs, insure that these leads are free from ringing and other conditions that would forward bias the chip's protection diodes.

There are three distinct modes of operation:

- Normal operating mode with all circuitry powered up. Typical supply current from V_{CC} is 35µA while only leakage currents flow from the battery.
- 2) Battery-backup mode where V_{CC} is typically within 0.7V below VBATT. All circuitry is powered up and the supply current from the battery is typically less than 60μ A.
- 3) Battery-backup mode where V_{CC} is less than VBATT by at least 0.7V. VBATT supply current is 1µA max.

Using SuperCap or MaxCap with the MAX691A/MAX693A/MAX800L/MAX800M

VBATT has the same operating voltage range as V_{CC}, and the battery switchover threshold voltages are typically \pm 30mV centered at VBATT, allowing use of a SuperCap and a simple charging circuit as a backup source (Figure 9).

If V_{CC} is above the reset threshold and VBATT is 0.5V above V_{CC}, current flows to V_{OUT} and V_{CC} from VBATT until the voltage at VBATT is less than 0.5V above V_{CC}. For example, with a SuperCap connected to VBATT and through a diode to V_{CC}, if V_{CC} quickly changes from 5.4V to 4.9V, the capacitor discharges through V_{OUT} and V_{CC} until VBATT reaches 5.1V typ. Leakage current through the SuperCap charging diode and the internal power diode eventually discharges the SuperCap to V_{CC}. Also, if V_{CC} and VBATT start from 0.1V above the reset thresh-



Figure 9. SuperCap or MaxCap on VBATT



Figure 10. Alternate CE Gating

old and power is lost at V_{CC}, the SuperCap on VBATT discharges through V_{CC} until VBATT reaches the reset threshold; then the battery-backup mode is initiated and the current through V_{CC} goes to zero.

Using Separate Power Supplies for VBATT and $\ensuremath{\mathsf{V}_{CC}}$

If using separate power supplies for V_{CC} and VBATT, VBATT must be less than 0.3V above V_{CC} when V_{CC} is above the reset threshold. As described in the previous section, if VBATT exceeds this limit and power is lost at V_{CC}, current flows continuously from VBATT to V_{CC} via the VBATT-to-V_{OUT} diode and the V_{OUT}-to-V_{CC} switch until the circuit is broken (Figure 8).

Alternate Chip-Enable Gating

Using memory devices with both CE and \overline{CE} inputs allows the CE loop to be bypassed. To do this, connect \overline{CE} IN to ground, pull up \overline{CE} OUT to V_{OUT}, and connect \overline{CE} OUT to the \overline{CE} input of each memory device (Figure 10). The CE input of each part then connects directly to the chip-select logic, which does not have to be gated.

Microprocessor Supervisory Circuits



Figure 11. Adding Hysteresis to the Power-Fail Comparator



Figure 12. Monitoring a Negative Voltage

Microprocessor Supervisory Circuits



Figure 13. Maximum Transient Duration without Causing a Reset Pulse vs. Reset Comparator Overdriv

Adding Hysteresis to the Power-Fail Comparator

Hysteresis adds a noise margin to the power-fail comparator and prevents repeated triggering of \overline{PFO} when V_{IN} is near the power-fail comparator trip point. Figure 11 shows how to add hysteresis to the power-fail comparator. Select the ratio of R1 and R2 such that PFI sees 1.25V when V_{IN} falls to the desired trip point (V_{TRIP}). Resistor R3 adds hysteresis. It will typically be an order of magnitude greater than R1 or R2. The current through R1 and R2 should be at least 1µA to ensure that the 25nA (max) PFI input current does not shift the trip point. R3 should be larger than 10k Ω to prevent it from loading down the \overline{PFO} pin. Capacitor C1 adds noise rejection.

Monitoring a Negative Voltage

The power-fail comparator can be used to monitor a negative supply voltage using Figure 12's circuit. When the negative supply is valid, \overline{PFO} is low. When the negative supply voltage drops, \overline{PFO} goes high. This circuit's

accuracy is affected by the PFI threshold tolerance, the V_{CC} voltage, and resistors R1 and R2.

Backup-Battery Replacement

The backup battery may be disconnected while V_{CC} is above the reset threshold. No precautions are necessary to avoid spurious reset pulses.

Negative-Going V_{CC} Transients

While issuing resets to the μ P during power-up, powerdown, and brownout conditions, these supervisors are relatively immune to short-duration, negative-going V_{CC} transients (glitches). It is usually undesirable to reset the μ P when V_{CC} experiences only small glitches.

Figure 13 shows maximum transient duration vs. resetcomparator overdrive, for which reset pulses are **not** generated. The graph was produced using negativegoing V_{CC} pulses, starting at 5V and ending below the reset threshold by the magnitude indicated (reset comparator overdrive). The graph shows the maximum pulse width a negative-going V_{CC} transient may typically have without causing a reset pulse to be issued. As the amplitude of the transient increases (i.e., goes farther below the reset threshold), the maximum allowable pulse width decreases. Typically, a V_{CC} transient that goes 100mV below the reset threshold and lasts for 40µs or less will not cause a reset pulse to be issued.

A 100nF bypass capacitor mounted close to the $V_{CC}\xspace$ pin provides additional transient immunity.

Connecting a Timing Capacitor at OSC IN

When OSC SEL is connected to ground, OSC IN disconnects from its internal $10\mu A$ (typ) pullup and is internally connected to a $\pm 100nA$ current source. When a capacitor is connected from OSC IN to ground (to select alternative reset and watchdog timeout periods), the current source charges and discharges the timing capacitor to create the oscillator that controls the reset and watchdog timeout period. To prevent timing errors or oscillator startup prob-

Microprocessor Supervisory Circuits

lems, minimize external current leakage sources at this pin, and locate the capacitor as close to OSC IN as possible. The sum of PC-board leakage plus OSC capacitor leakage must be small compared to ±100nA.

Maximum V_{CC} Fall Time

The V_{CC} fall time is limited by the propagation delay of the battery switchover comparator and should not exceed 0.03V/µs. A standard rule of thumb for filter capacitance on most regulators is on the order of 100µF per amp of current. When the power supply is shut off or the main battery is disconnected, the associated initial V_{CC} fall rate is just the inverse or 1A/100µF = 0.01V/µs. The V_{CC} fall rate decreases with time as V_{CC} falls exponentially, which more than satisfies the maximum fall-time requirement.

Watchdog Software Considerations

A way to help the watchdog timer keep a closer watch on software execution involves setting and resetting the watchdog input at different points in the program, rather than "pulsing" the watchdog input high-low-high or lowhigh-low. This technique avoids a "stuck" loop where the watchdog timer continues to be reset within the loop, keeping the watchdog from timing out. Figure 14 shows an example flow diagram where the I/O driving the watchdog input is set high at the beginning of the program, set low at the beginning of every subroutine or loop, then set high again when the program returns to the beginning. If the program should "hang" in any subroutine, the I/O is continually set low and the watchdog timer is allowed to time out, causing a reset or interrupt to be issued.



Figure 14. Watchdog Flow Diagram

MAX691A/MAX693A/ MAX800L/MAX800M

Ordering Information (continued)

PART	TEMP RANGE	PIN- PACKAGE
MAX691AEJE	-40°C to +85°C	16 CERDIP
MAX691AMJE	-55°C to +125°C	16 CERDIP**
MAX691AMSE/PR	-55°C to +125°C	16 Narrow SO**
MAX691AMSE/PR-T	-55°C to +125°C	16 Narrow SO**
MAX693ACUE	-0°C to +70°C	16 TSSOP
MAX693ACSE	-0°C to +70°C	16 Narrow SO
MAX693ACWE	-0°C to +70°C	16 Wide SO
MAX693ACPE	-0°C to +70°C	16 Plastic DIP
MAX693AC/D	-0°C to +70°C	Dice*
MAX693AEUE	-40°C to +85°C	16 TSSOP
MAX693AESE	-40°C to +85°C	16 Narrow SO
MAX693AEWE	-40°C to +85°C	16 Wide SO
MAX693AEPE	-40°C to +85°C	16 Plastic DIP
MAX693AEJE	-40°C to +85°C	16 CERDIP
MAX693AMJE	-55°C to +125°C	16 CERDIP
MAX800LCUE	-0°C to +70°C	16 TSSOP
MAX800LCSE	-0°C to +70°C	16 Narrow SO
MAX800LCPE	-0°C to +70°C	16 Plastic DIP
MAX800LEUE	-40°C to +85°C	16 TSSOP
MAX800LESE	-40°C to +85°C	16 Narrow SO
MAX800LEPE	-40°C to +85°C	16 Plastic DIP
MAX800MCUE	-0°C to +70°C	16 TSSOP
MAX800MCSE	-0°C to +70°C	16 Narrow SO
MAX800MCPE	-0°C to +70°C	16 Plastic DIP
MAX800MEUE	-40°C to +85°C	16 TSSOP
MAX800MESE	-40°C to +85°C	16 Narrow SO
MAX800MEPE	-40°C to +85°C	16 Plastic DIP

*Dice are specified at T_A = +25°C, DC parameters only.

**Contact factory for availability and processing to MIL-STD-883B.

Devices in PDIP, SO and TSSOP packages are available in both leaded and lead-free packaging. Specify lead free by adding the + symbol at the end of the part number when ordering. Lead free not available for CERDIP package.

Chip Topography



Package Information

For the latest package outline information and land patterns (footprints), go to <u>www.maximintegrated.com/packages</u>. Note that a "+", "#", or "-" in the package code indicates RoHS status only. Package drawings may show a different suffix character, but the drawing pertains to the package regardless of RoHS status.

PACKAGE TYPE	PKG CODE	OUTLINE NO.	LAND PATTERN NO.
16 TSSOP	U16-1	<u>21-0066</u>	<u>90-0117</u>
16 CERDIP	J16-3	<u>21-0045</u>	=
16 Narrow SO	S16-3	21-0041	90-0097
16 Plastic DIP	P16-1	<u>21-0043</u>	=
16 Wide SO	W16-1	21-0042	90-0107

Microprocessor Supervisory Circuits

Revision History

REVISION NUMBER	REVISION DATE	DESCRIPTION	PAGES CHANGED
0	09/92	Initial release	—
1	12/92	Update Electrical Characteristics table.	2, 3, 4
2	5/93	Update Electrical Characteristics table, Tables 1 and 2.	2, 3, 4, 9, 11
3	12/93	Update Electrical Characteristics table.	2, 3, 4
4	3/94	Update Electrical Characteristics table.	2, 3, 4
5	8/94	Correction to Figure 4.	10
6	1/95	Update to new revision and correct errors.	—
7	12/96	Update Electrical Characteristics table.	2, 3, 4
8	12/99	Updated Ordering Information, Pin Configuration, Absolute Maximum Ratings, and Package Information.	1, 2, 16
9	4/02	Corrected Ordering Information.	1
10	11/05	Added lead-free information.	1, 16
11	8/08	Updated Ordering Information.	1, 16
12	9/14	No /V OPNs; removed automotive reference from <i>Applications</i> section; updated <i>Package Information</i> table	1, 16
13	11/17	Updated Electrical Characteristics table	2
14	4/18	Updated Ordering Information table	16

For pricing, delivery, and ordering information, please contact Maxim Direct at 1-888-629-4642, or visit Maxim Integrated's website at www.maximintegrated.com.

Maxim Integrated cannot assume responsibility for use of any circuitry other than circuitry entirely embodied in a Maxim Integrated product. No circuit patent licenses are implied. Maxim Integrated reserves the right to change the circuitry and specifications without notice at any time. The parametric values (min and max limits) shown in the Electrical Characteristics table are guaranteed. Other parametric values quoted in this data sheet are provided for guidance.

Mouser Electronics

Authorized Distributor

Click to View Pricing, Inventory, Delivery & Lifecycle Information:

Maxim Integrated:

MAX691ACPE+ MAX691ACSE+ MAX691ACWE+ MAX691AEPE+ MAX691AESE+ MAX691AEWE+ MAX693ACPE+ MAX693ACSE+ MAX693AEPE+ MAX800LCPE+ MAX800LCSE+ MAX800LCSE+T MAX800LCUE+ MAX800LCUE+T MAX800LEUE+ MAX800LEUE+T MAX800MCPE+ MAX800MCSE+ MAX800MCSE+T MAX800MCUE+ MAX800MCUE+T MAX800MEUE+ MAX800MEUE+T MAX691ACSE+T MAX691ACUE+ MAX691ACUE+T MAX691ACWE+T MAX691AESE+T MAX691AEUE+ MAX691AEUE+T MAX691AEWE+T MAX693ACSE+T MAX693ACUE+ MAX693ACUE+T MAX693ACWE+ MAX693ACWE+T MAX693AESE+ MAX693AESE+T MAX693AEUE+ MAX693AEUE+T MAX693AEWE+ MAX693AEWE+T MAX693AMJE MAX691AMSE/PR-T MAX691AMSE/PR MAX691AEJE MAX800LESE+ MAX691AMJE/883B MAX693ACUE MAX800LESE MAX691ACUE